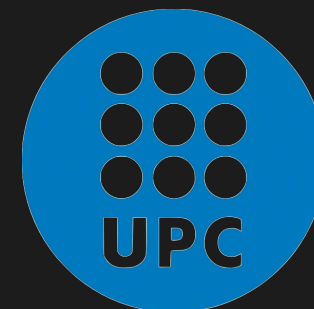


master degree in  
Telecommunication Engineering



# UAV-based GNSS-R Systems for Soil Moisture Monitoring

student

Tommaso Martini

advisors

Luca Schenato

Adriano Camps

tutor

Alberto Alonso

# 1 the laboratory

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# Remote Sensing Laboratory



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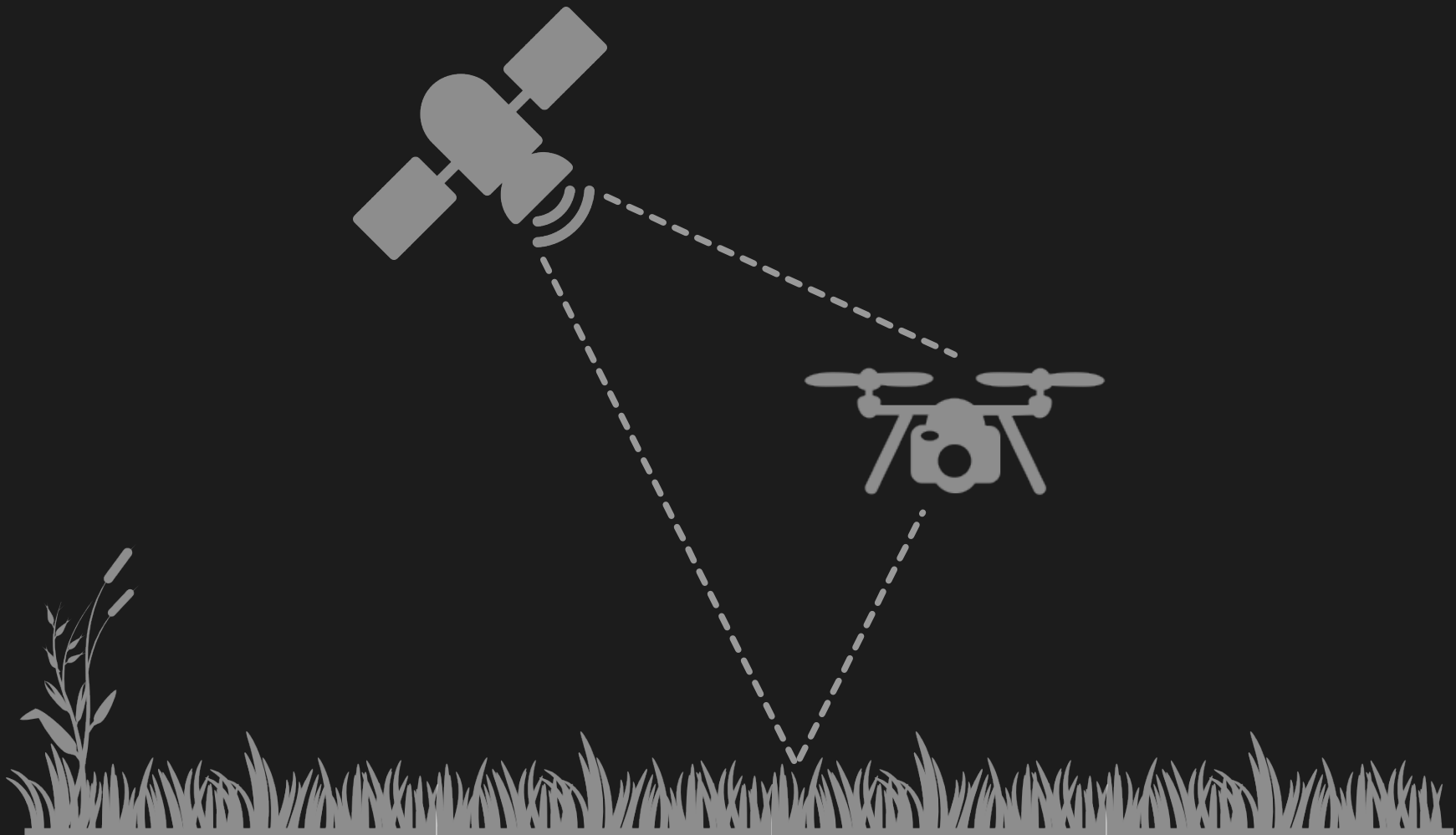
# GNSS-R

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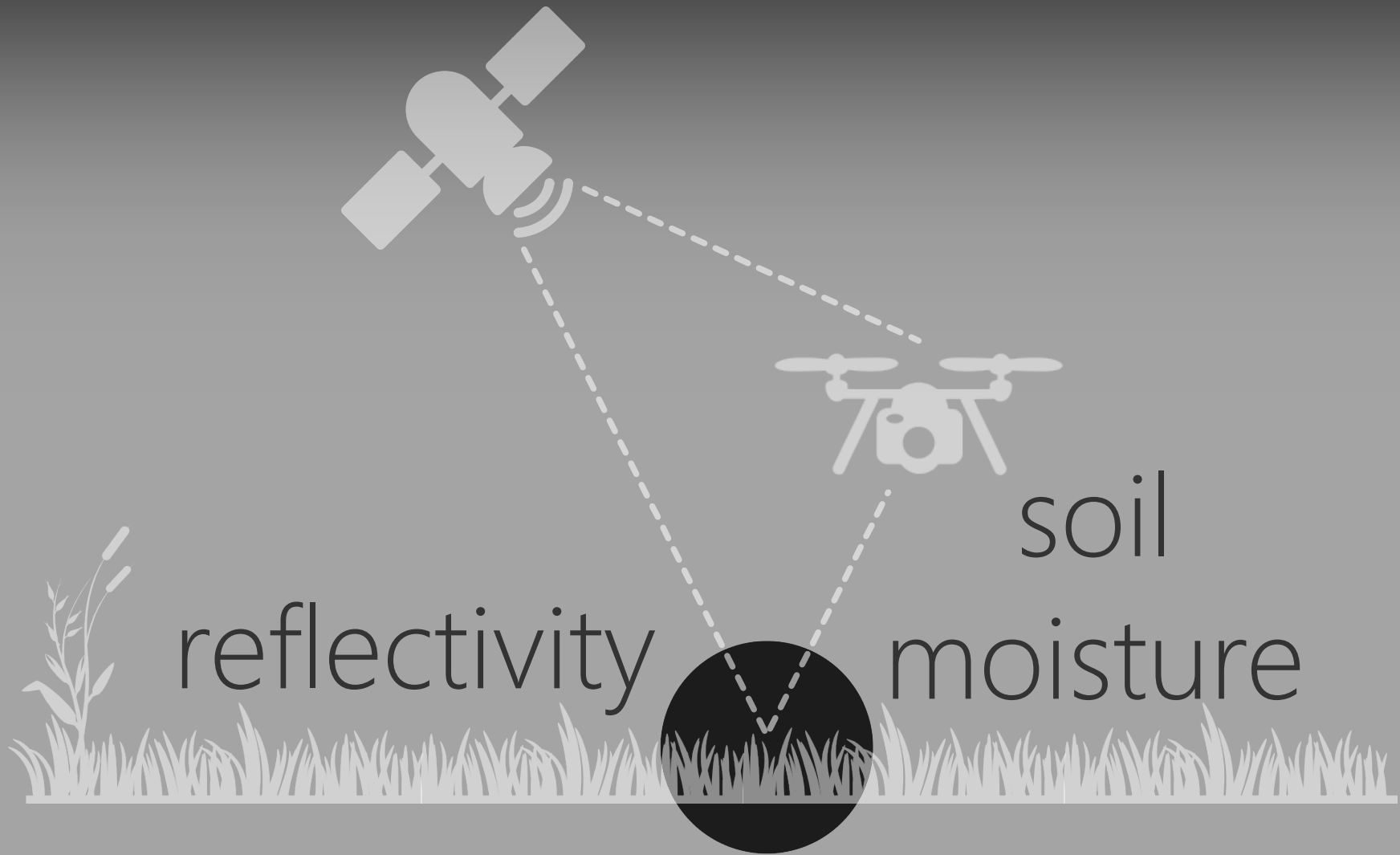


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state of the art

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# Light Airborne Reflectometer for GNSS-R Observations



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# state of the art

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# Light Airborne Reflectometer for GNSS-R Observations



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UAV-based

lighter  
smaller

4

goals

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UAV-based real-time

lighter  
smaller

faster  
smarter



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# my contribution

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# my contribution

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hardware



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# my contribution

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hardware

software



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# my contribution

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hardware

software

field campaign

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# my contribution

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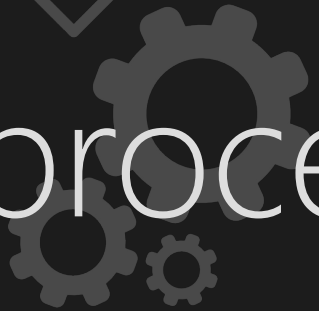
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## Compact Reflectometer for Terrain Observations

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# my contribution

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Compact Reflectorimeter  
for Terrain Observations

# CORRTO

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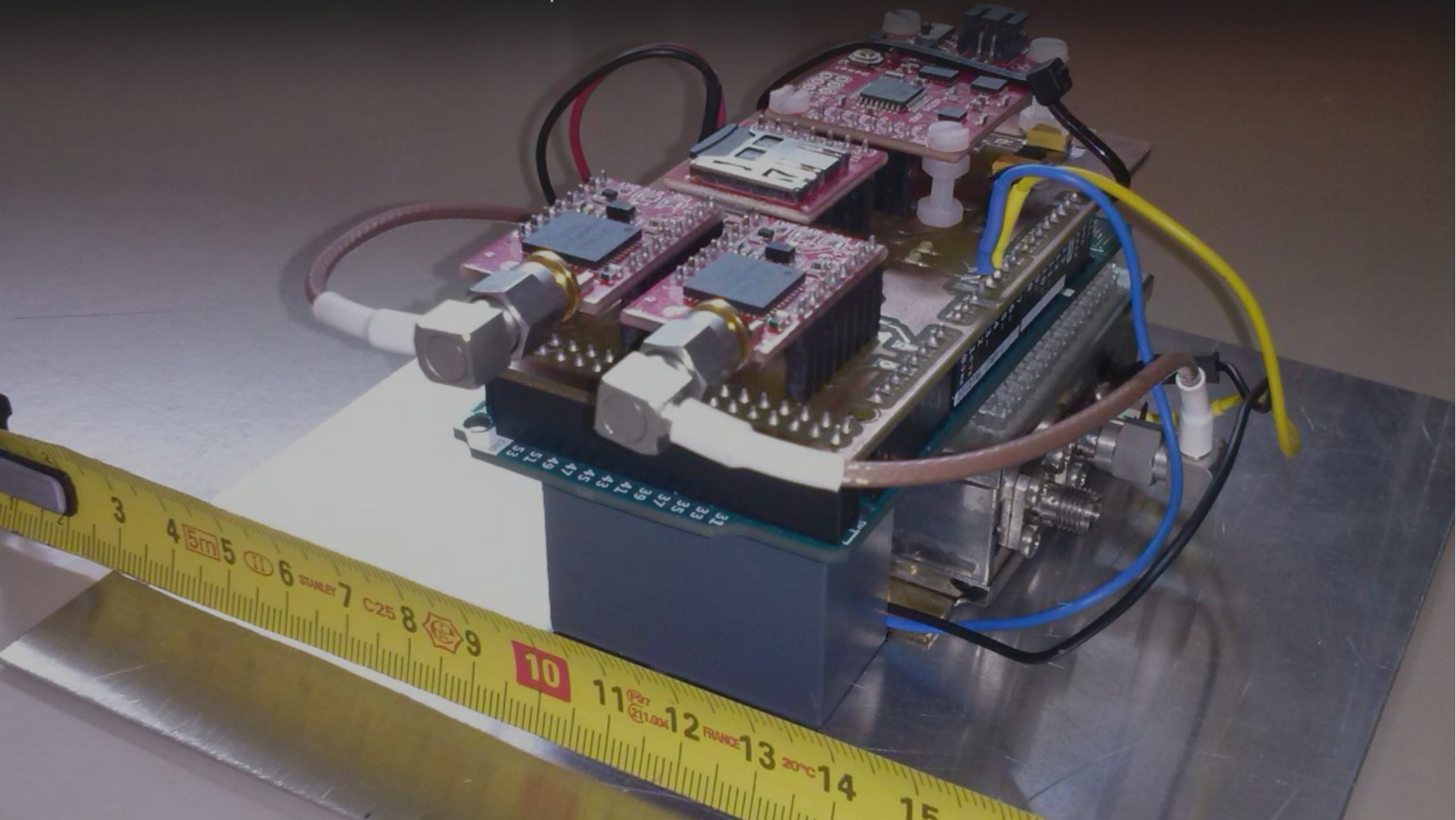
# hardware

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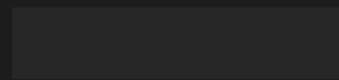
# software

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# field campaign

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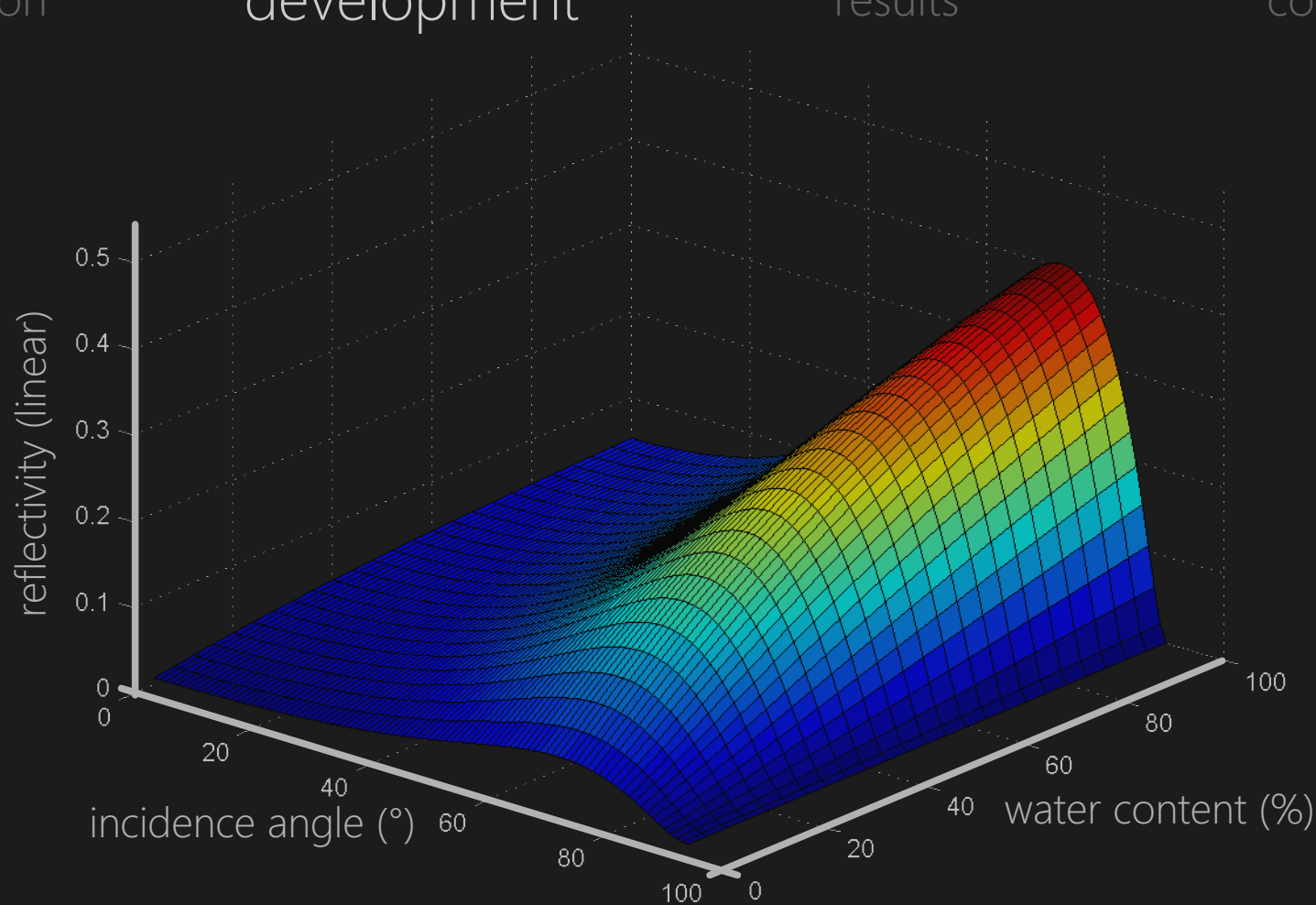


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$$\Gamma_{RHCP,LHCP}(SM, \theta_i) = \left| \frac{\rho_{TE}(SM, \theta_i) - \rho_{TM}(SM, \theta_i)}{2} \right|^2 e^{-4k^2 \sigma^2 \cos^2 \theta_i}$$

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# weight

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LARGO

CORTO

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# space

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LARGO



CORTO

17.5 Mbytes/h



LARGO

1.1 Mbytes/h



CORTO

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LARGO



CORTO

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# performance

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## CORTO

### LARGO

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# UAV-based GNSS-R Systems for Soil Moisture Monitoring

by  
Tommaso Martini

Padova, October 6th 2015