

$$\begin{aligned} & \hat{h}_{\mathcal{H}_K}^{[i]} \\ & \hat{K}_K^{[i]} \\ & \hat{h}_{\hat{K}}^{[i]} \\ & h^{[i]} \\ \{ \hat{h}^{[i]} \} = \arg \min_{h^{[i]} \in \mathcal{H}_K} & \sum_{t=t_0}^N (y_t - \hat{y}_{t|t-1})^2 + \gamma_2^2 \left(\sum_{i=1}^m \|h^{[i]}\|_{\mathcal{H}_K}^2 \right) \end{aligned}$$

$$(1) \quad \hat{y}_{t|t-1} = \sum_{i=1}^{m-1} \left[\sum_{k=1}^{\infty} h_k^{[i]} u_{t-k}^{[i]} \right] + \sum_{k=1}^{\infty} h_k^{[m]} y_{t-k}.$$

$$\begin{aligned} & \hat{h}_{\hat{K}}^{[i]} \\ & \hat{K}_K^{[i]} = \\ & 0, \forall k > \\ & \hat{J} \\ & \hat{K}_J^J(h, k) = \\ & 0, \forall (h, k) : \\ & k > \\ & Joppureh > \\ & \underline{h}^{[i]} := [h_1^{[i]}, h_2^{[i]}, \dots, h_{t_0}^{[i]}]^T. \end{aligned}$$

$$\begin{aligned} & \hat{K}_J \in \\ & R^{j \times j} \\ & \|h^{[i]}\|_{\mathcal{H}_{K_J}}^2 \\ & \|h^{[i]}\|_{\mathcal{H}_{K_J}}^2 = (\underline{h}^{[i]})^T K_J^{-1} \underline{h}^{[i]}. \end{aligned}$$

$$(3) \quad \hat{y}_{t|t-1} = \sum_{i=1}^{m-1} \left[\sum_{k=1}^J h_k^{[i]} u_{t-k}^{[i]} \right] + \sum_{k=1}^J h_k^{[m]} y_{t-k}.$$

$$\begin{aligned} & \underline{h}^{[i]} \in \\ & \mathcal{H}_{K_J} \\ & ?? \\ & \arg \min_{\underline{h}^{[i]} \in R^{t_0}} \sum_{t=t_0}^N (y_t - \hat{y}_{t|t-1})^2 + \gamma_2^2 \sum_{i=1}^m \left[(\underline{h}^{[i]})^T K_J^{-1} \underline{h}^{[i]} \right] \end{aligned}$$

$$(4) \quad \begin{aligned} & ?? \\ & \dot{\underline{h}}_{t_0}^{[i]} \\ & \underline{h}_{t_0}^{[i]} \\ & ?? \\ & l_2 \\ & \bar{y}_{t_0}^+ = \sum_{i=1}^m \bar{A}_{Ji} h_{t_0}^{[i]} + W \end{aligned}$$

$$(5) \quad \begin{aligned} & \bar{y}_{t_0}^+ := \\ & \underline{y}_{t_0}^+ \\ & 0_{1 \times (t_0 \cdot m)} \\ & \bar{A}_{Ji} := \\ & [A_{Ji} v_i \otimes \Lambda] \Lambda := \\ & \gamma_2 K_J^{-1/2} \\ & \underline{v}_i^+ := \\ & [\underbrace{0 \dots 0}_{i-1} \underbrace{1 0 \dots 0}_{m-i}]^T \\ & \beta \\ & ?? \\ & \dot{\bar{A}}_{Ji} \\ & \dot{\underline{h}}_{t_0}^{[i]} \\ & \dot{\gamma}_2^2 \\ & l_2 \\ & ?? \\ & [\underline{h}_1^{[i]}, \underline{h}_2^{[i]}, \dots, \underline{h}_{t_0}^{[i]}]^T \\ & \mathcal{H}_{K_{t_0}} \\ & \beta \\ & \{y_t, u_t\}_{t=1, \dots, N} \\ & \{y_t, u_t\}_{t=1, \dots, 2N/3} \\ & \langle \dots \rangle \end{aligned}$$