

## **SHTxx** Humidity & Temperature Sensmitter

# Application Note Non-Linearity compensation

## 1 Introduction

The SHTxx devices show a small non-linearity of the humidity and temperature sensors. This application note describes various ways to compensate it in the attached microcontroller.

## 2 Relative Humidity Non Linearity

If the formula given in the datasheet is too complex and therefore too computation intense, the following calculations may provide simplified alternatives.

Type of calculation	Inaccuracy due to non-linearity (10-90%RH) V4 Coefficients	Inaccuracy due to non-linearity (10-90%RH) V3 Coefficients	Complexity of calculation
Simple linearization	± 1.6% RH	± 2.2% RH	Simple (8bit subtract, right shift)
Two segment linearization	± 0.6% RH	± 0.8% RH	Quite simple (8bit multiplication, 16bit add/subtract)
Polynomial 2 <sup>nd</sup> order	± 0.1% RH	± 0.1% RH	Floating point multiplications

New coefficients have been introduced and provide optimized accuracy for V4 sensors along the full measurement range. In this application note the old sets of parameters are marked with an asterisk. They have been proposed in earlier datasheets and are optimized for V3 sensors, but could still be applied to V4 version. V4 sensors can be identified by the alpha-numeric traceability code on the sensor cap instead of the 3 digit numeric code indicating V3 sensors.

## 2.1 Simple Humidity Linearization

The most basic conversion formula from sensor output to RH is given in the following. The coefficients e and f have to be chosen according to table 1 as set of (e, f) or (e<sup>\*</sup>, f<sup>\*</sup>) respectively.

#### $RH_{linear} = e + f \bullet SO_{RH}$ (%RH)

	Versi	on V4	Version V3	
SORH	е	f	e*	f*
12 bit	1.165	0.0314	0.5	0.0314
8 bit	1.165	0.5	0.5	0.5

Table 1: Coefficients for simple linearization

#### 2.2 Two segment humidity linearization

For improved accuracy with minimal calculation complexity the following calculation is recommended. The coefficients a and b have to be chosen according to table 3 for 8 bit  $SO_{RH}$  readout or table 4 for 12 bit  $SO_{RH}$  readout as set of (a, b) or (a\*, b\*) respectively.

#### 8 bit SO<sub>RH</sub>

$$RH_{linear} = \frac{(a + b \bullet SO_{RH})}{256}$$
 (%RH)

	Versi	on V4	Version V3		
Validity Limits	а	b	a*	b*	
$0 \le SO_{RH} \le 107$	-230	138	-512	143	
$108 \le SO_{RH} \le 255$	1306	122	2893	111	

Table 3: Two segment humidity linearization coefficients for 8 bit resolution

#### 12 bit SO<sub>RH</sub>

$$RH_{linear} = \frac{(a + b \bullet SO_{RH})}{4096}$$
 (%RH)

	Versi	on V4	Versi	on V3
Validity Limits	а	b	a*	b*
$0 \le SO_{RH} \le 1712$	-3680	138	-8192	143
$1713 \leq SO_{RH} \leq 4096$	20896	122	46288	111

Table 4: Two segment humidity linearization coefficients for 12 bit resolution

See Appendix A for a 8 bit SO<sub>RH</sub> sample code.

#### 2.3 Polynomial 2<sup>nd</sup> order

This linearization method is according to the datasheet SHT1x and SHT7x. The coefficients  $c_x$  have to be chosen according to table 5 as set of  $c_x$  or  $c_x^*$  respectively.

$RH_{linear}$	$= C_1 + C_1$	2 • SO <sub>RH</sub> -	$+ c_3 \cdot SO_F$	<sub>RH</sub> <sup>2</sup> (%RH)
• • • Iinear	$-0_{1}$	$2 $ $\Theta $ $\Theta $ RH	103 00F	

	Version V4			Version V4 Version V3		
SORH	<b>C</b> 1	C2	<b>C</b> 3	C1*	C2*	C3*
12 bit	-2.0468	0.0367	-1.5955E-6	-4.0000	0.0405	-2.8000E-6
8 bit	-2.0468	0.5872	-4.0845E-4	-4.0000	0.6480	-7.2000E-4

Table 5: Coefficients for humidity linearization with polynomial of second order

## 3 Temperature Non Linearity

Due to the inherent properties of the band gap PTAT (Proportional To Absolute Temperature) temperature sensor, the temperature output signal is not fully linear. The correction formula results in a correction of about -1°C at -40°C and -1 °C at 100°C compared to the linear formula. The parameter setting is the same for version V4 sensors as for version V3 sensors.

 $T = d_1 + d_2 \bullet SO_T + d_3 \bullet (SO_T - g)^2$ 

VDD	d₁ [°C]	d₁[°F]
5V	-40.1	-40.2
4V	-39.8	-39.6
3.5V	-39.7	-39.5
3V	-39.6	-39.3
2.5V	-39.4	-38.9

SOT	d <sub>2</sub> [°C]	d₂[°F]	d₃[°C]	d₃ [°F]	g
14bit	0.01	0.018	-2e-8	-3.6e-8	7000
12bit	0.04	0.072	-3.2e-7	-5.76e-7	1750

Table 6: Coefficients for temperature linearization with polynomial of second order

### 4 Revision History

Date	Revision	Changes
October 20, 2001	0.9 (Preliminary)	
February 10, 2002	1.0	modified to final coefficients
February 15, 2003	1.1	added Temperature information
Oct. 17, 2003	1.2	Changed download link
May 10, 2004	1.3	Added Temperature non linearity information
October 19, 2004	1.31	Added 16 bit information in chapter 2.2
May 25, 2005	1.32	Changed company address
Oct 3, 2006	1.4	Sensirion Inc. address added
July 22, 2008	1.5	New coefficients for V4, completely revised

The latest version of this document and all application notes can be found at: www.sensirion.com/humidity

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## Appendix A

Sample Code 8 bit SO<sub>RH</sub>:

```
// 16Bit unsigned for the result
ul6 result;
u08 sensor_out;
                      // 8Bit unsigned for the sensoroutput
sensor_out = readSensor8(); // read 8 bit humidity value from SHTxx
If ( sensor_out <= 107 )</pre>
{
   result = mult8Bit( 143, sensor_out ); // result = a * sensor_out
   result < 512 ? result = 512;
                                                  // check for underflow
                                                  // result = result + b
   result = result - 512
}
else
{
   result = mult8Bit( 111, sensor_out ); // result = a * sensor_out
result = result + 2893 // result = result + b
                                                  // result = result + b
// check for overflow (optional)
   result = result + 2893
   result > 25600 ? result = 25600;
}
//8 MSB's are 0-100%RH integers, 8 LSB's are remainder
result = result >> 8 // result = result / 256
```