



Distributed Synchronization Algorithms for Wireless Sensor Networks

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Nicola Varanese

Dipartimento di Elettronica e Informazione, Politecnico di Milano
<varanese@elet.polimi.it>



- ❑ Double-degree program between *PoliMi* and *New Jersey Institute of Tech.* (Newark, NJ)
- ❑ *PoliMi*: Prof. Umberto Spagnolini
- ❑ *NJIT*: Prof. Yeheskel Bar-Ness and Prof. Osvaldo Simeone

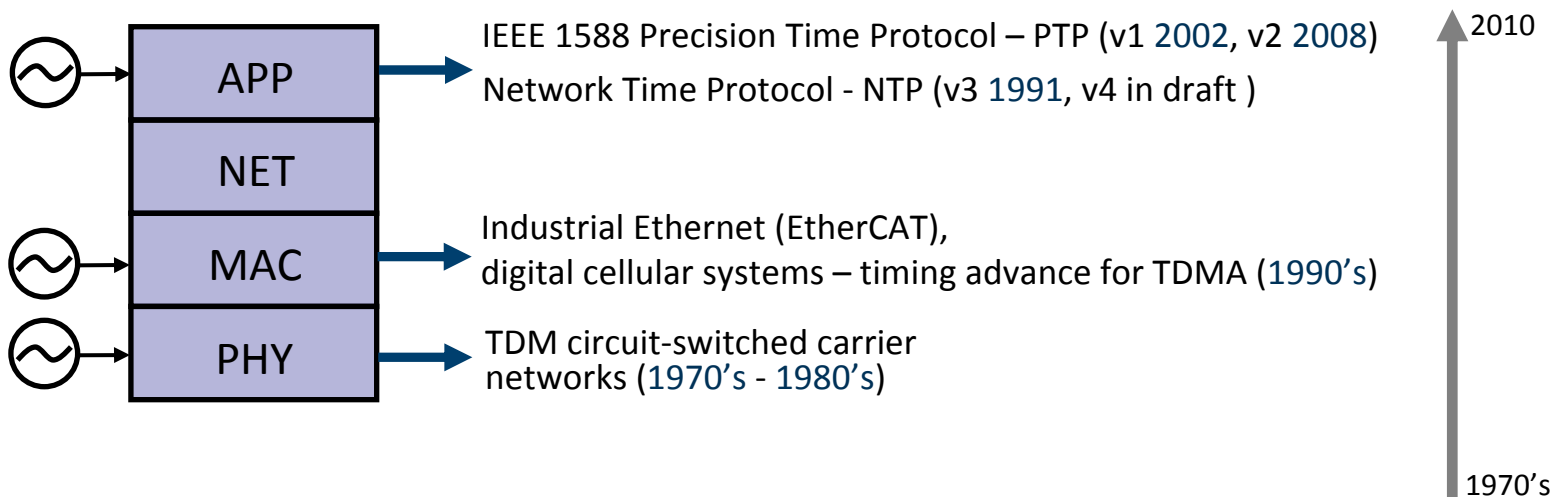


- Motivation
- Synchronization at the physical layer
- Synchronization at the MAC layer
- Conclusions



Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

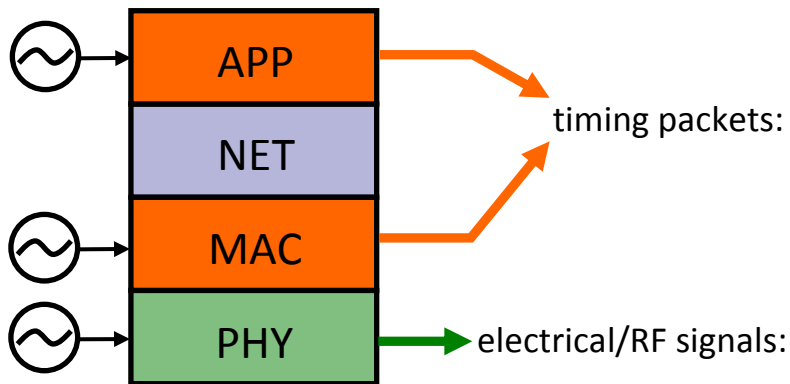
- Communication *Networks*:
synchronization at different layers





Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

- Communication *Networks*: synchronization at different layers



timing packets:

- *Software* PLL (linear clock control)
- Kalman tracking
- estimation of clock parameters (phase/frequency/drift)
- other (e.g., nonlinear clock correction)

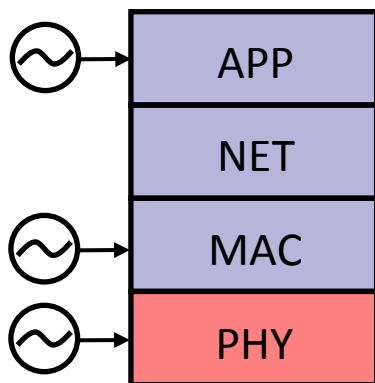
electrical/RF signals:

- Analogue Phase-locked Loop (APLL)
- (All) Digital PLL (DPLL)
- analogue/digital Frequency-locked Loop (FLL)

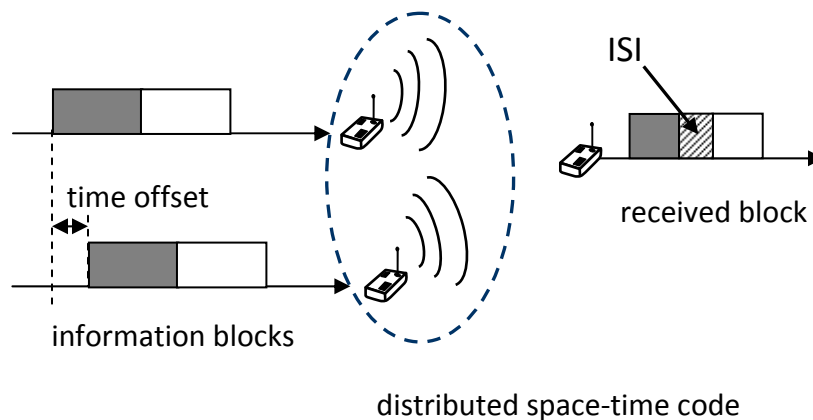


Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

- Wireless Sensor Networks:
synchronization at different layers



physical: cooperative communication

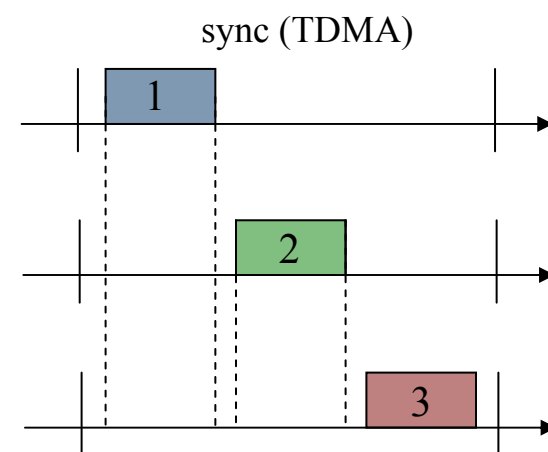
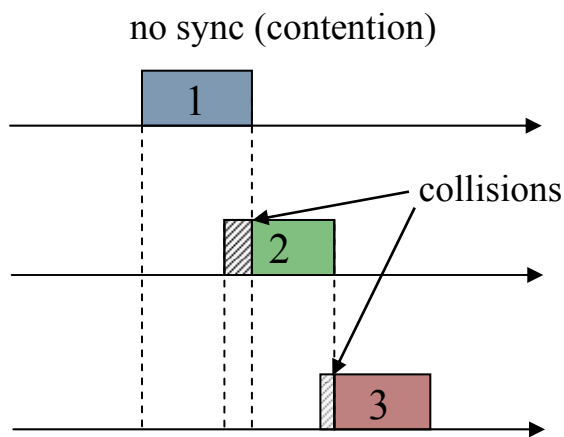
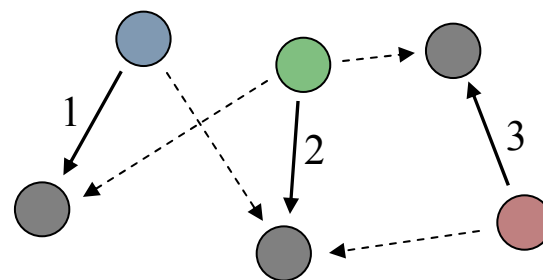
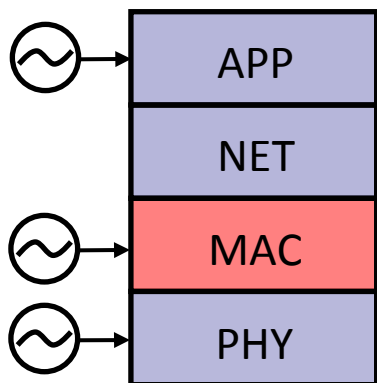




Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

- Wireless Sensor Networks: synchronization at different layers

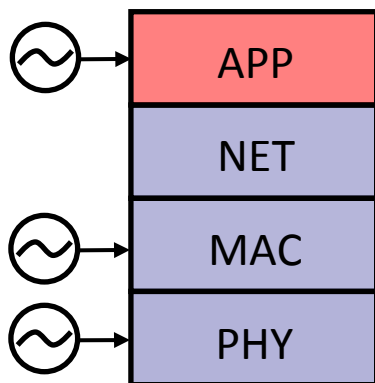
MAC: coordinated medium access



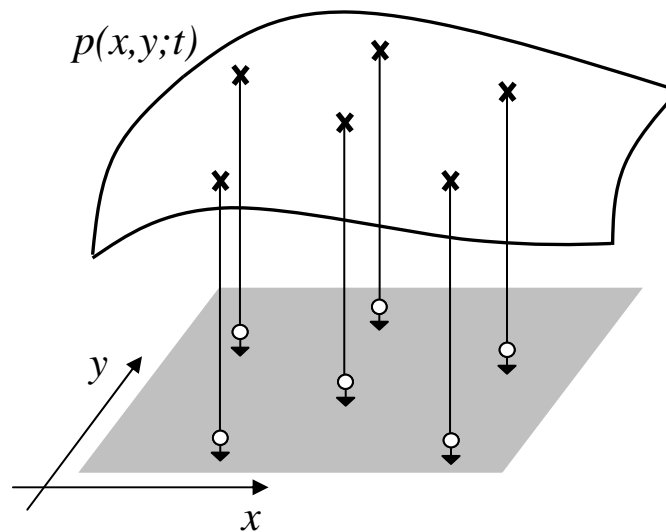


Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

- Wireless Sensor Networks:
synchronization at different layers

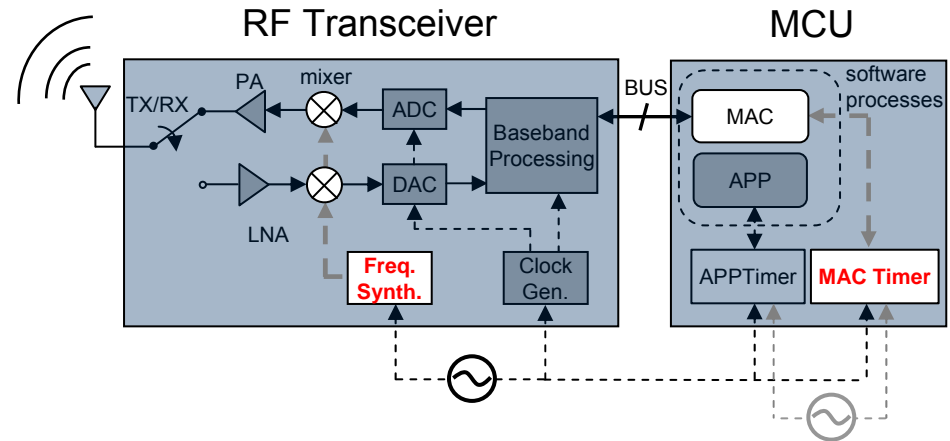
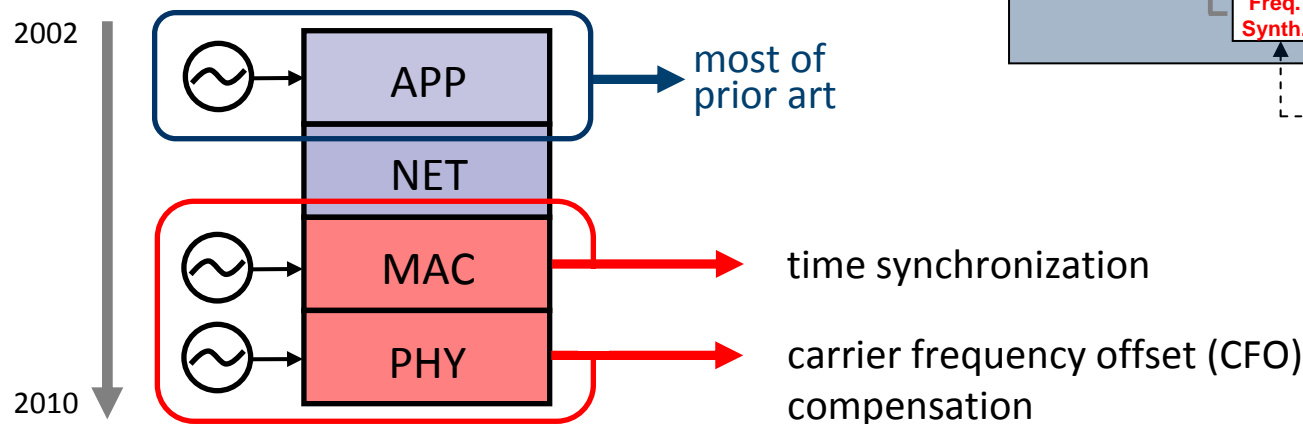


application: distributed sensing



Synchronization is the simplest form of cooperation and enables more complex cooperative tasks

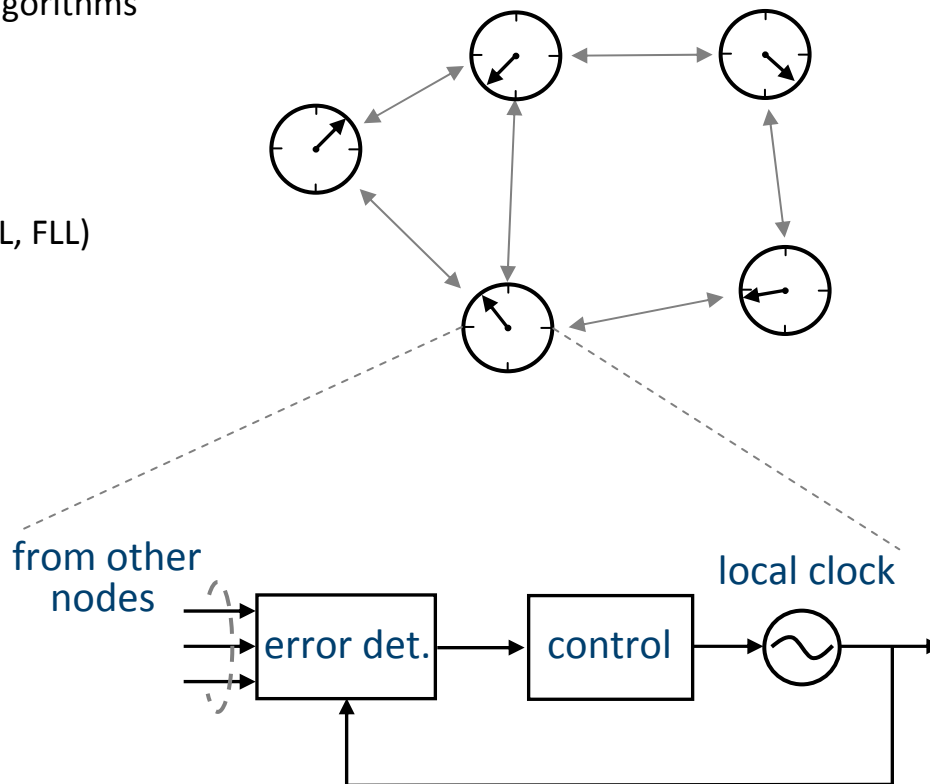
- Wireless Sensor Networks: synchronization at different layers





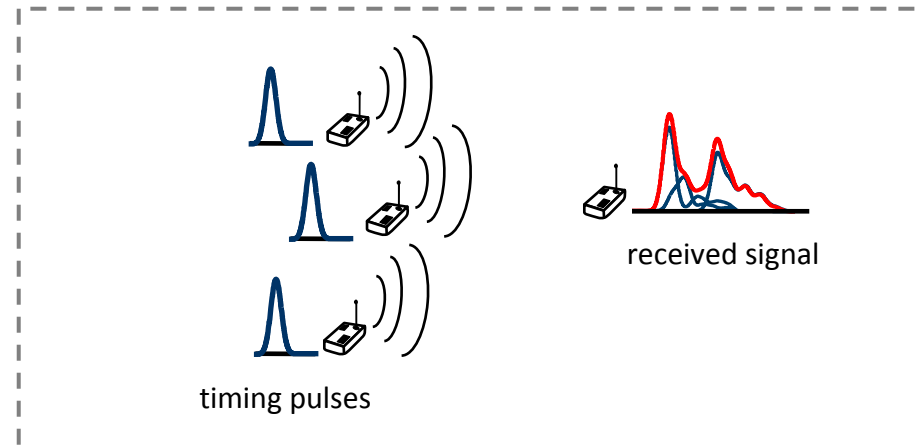
- Prior Art:
 - *estimation* of clock parameters [Kumar08][Estrin04]
 - distributed agreement (consensus) algorithms [Simeone07][Schenato09]
- Our approach:
control of the local clock
via Phase and Frequency-Locked Loops (PLL, FLL)

PLL is the classical approach for wired networks (TDM, NTP, PTP)
what about wireless ?

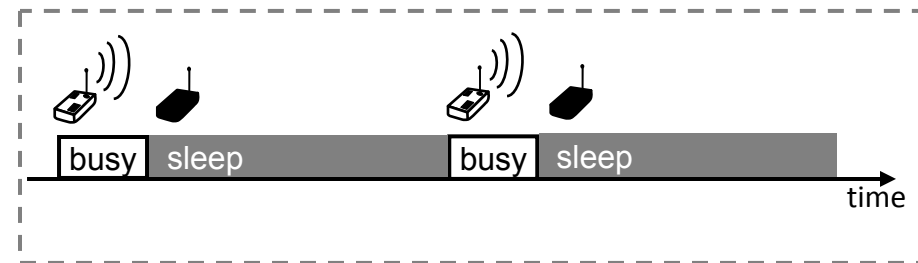
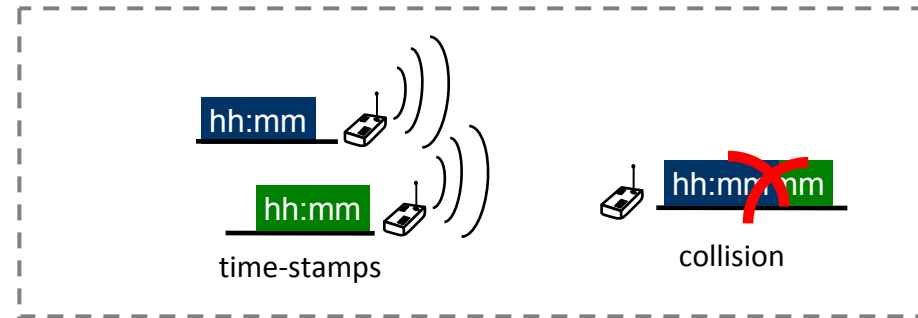




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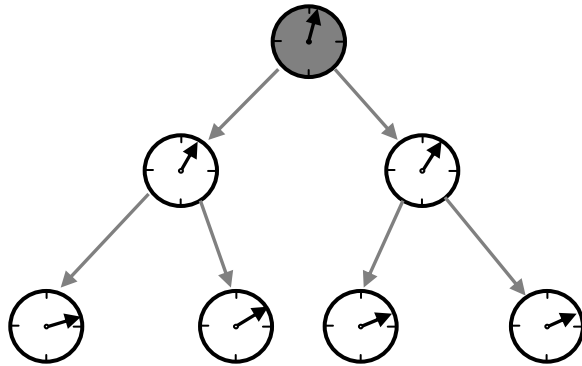


- Challenges:
 - superposition of radio signals
 - packet collisions
 - energy constraints (low duty cycles)



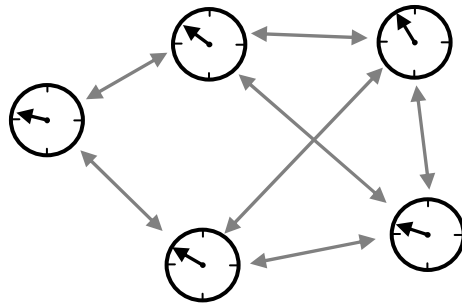


master-slave (MS): hierarchical

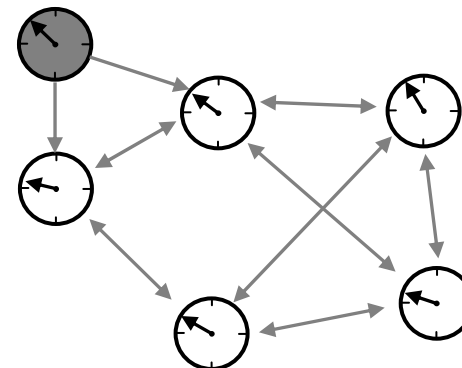


- WSN offer wider flexibility in sync architecture design
- Prior Art:
 - *specific* tools for each sync topology, e.g.
 - MS: linear regression (FTSP [Maróti04])
 - MC: distributed consensus (ATS [Schenato09])
- Our approach:
PLL/FLL as a *distributed* clock control tool suitable for *any* sync topology

mutually coupled (MC): peer-to-peer



hybrid



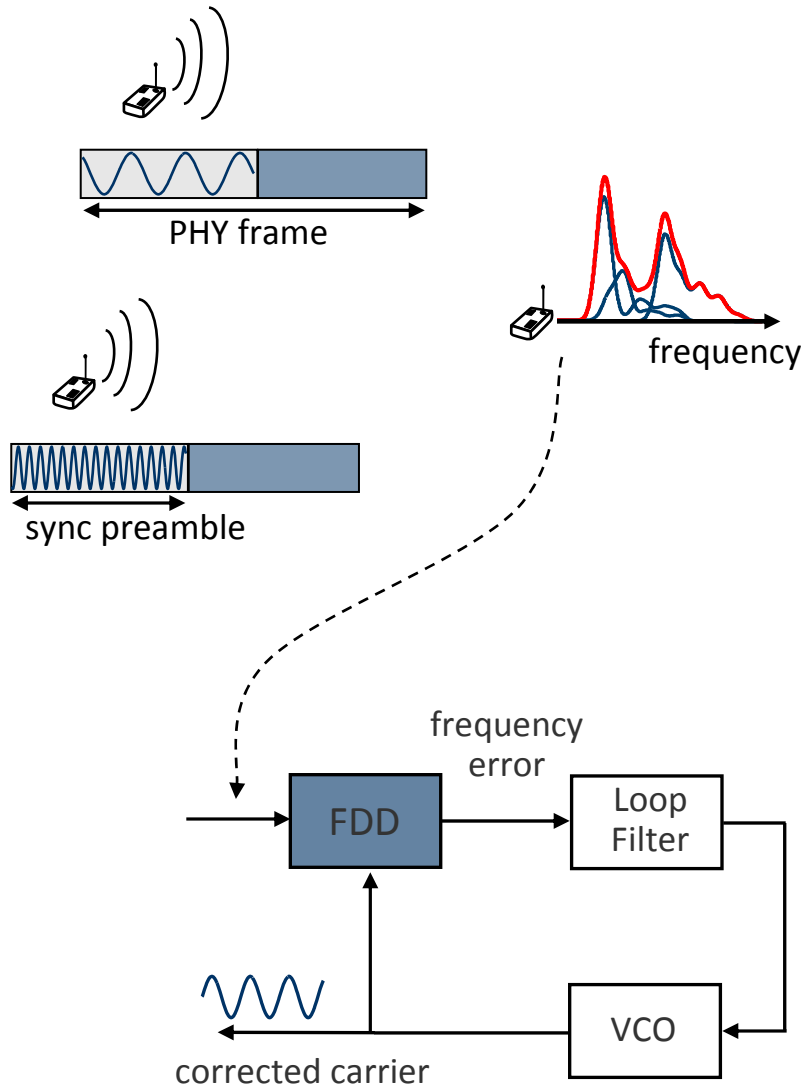


- ❑ Motivation

- ❑ Synchronization at the physical layer
 - ❑ distributed compensation of Carrier Frequency Offsets (CFO)

- ❑ Synchronization at the MAC layer

- ❑ Conclusions

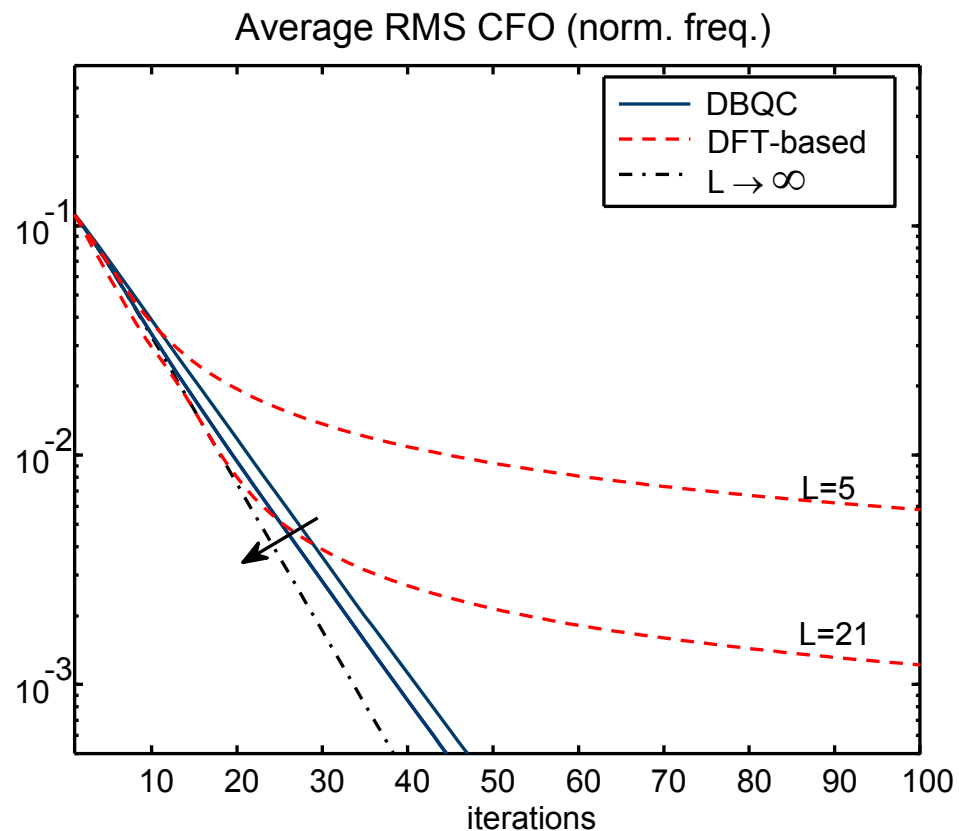
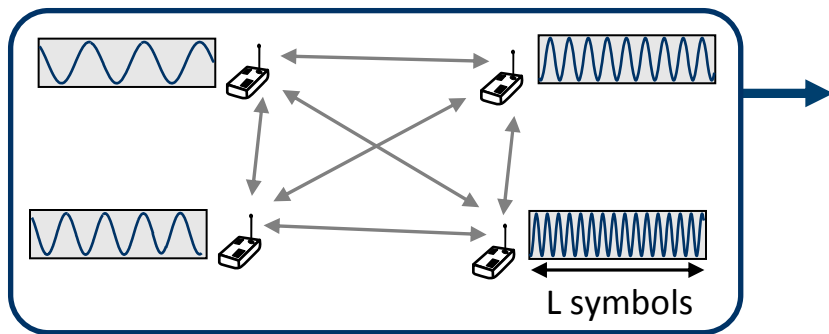


- Sync preamble for CFO estimation
- CFO correction via *distributed-FLL* (D-FLL)
- design of novel Frequency Difference Detector (FDD)
 - *superposition* of preamble signals
 - based on sample auto-correlation
 - nonlinear characteristic
- analysis:
 - frequency *acquisition* (stability and conv. speed)
 - steady-state sync *accuracy*



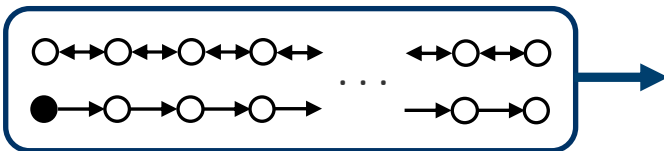
- frequency acquisition
 - FDD locking range
 - stability conditions (MC networks)
 - connectivity
 - mutual interference

- comparison with DFT-based FDD for a simple MC network

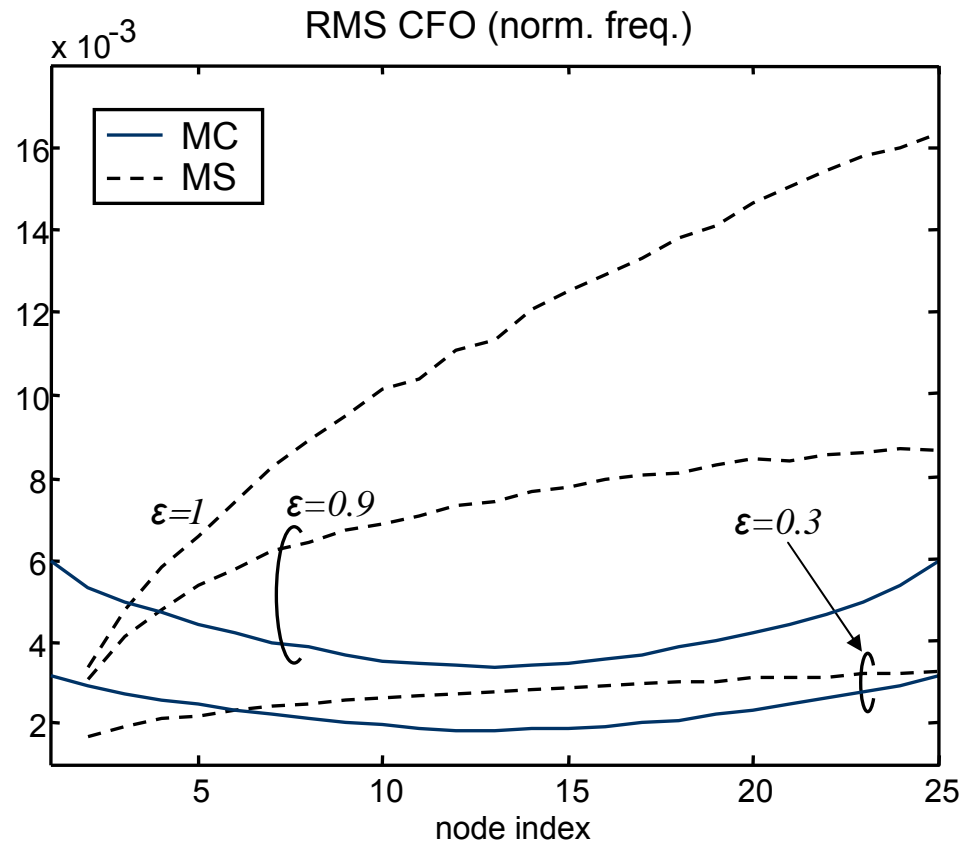
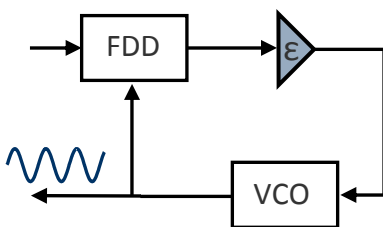




- Steady-state sync accuracy
 - channel noise and frequency instability (WFM)
 - MC and MS topologies
- residual CFO distribution in a MC and MS line network



- FLL bandwidth tuned via loop gain ϵ





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 - ❑ Sync tracking with low duty-cycles

- ❑ Conclusions

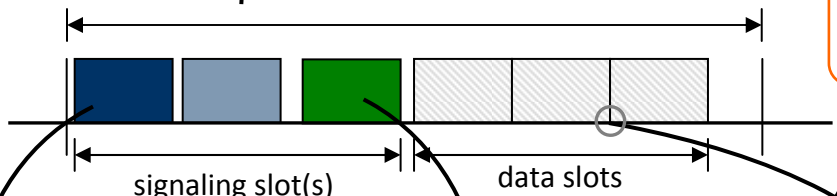


General SF structure

for a slotted-access MAC layer :



super-frame = sync update period
length

IEEE 802.15.4/e (ZigBee/SP100)
IEEE 802.11 (Wi-Fi)
ECMA 368 (WiMedia)

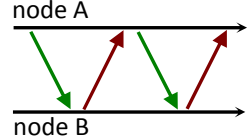


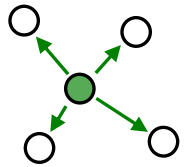
need for *time sync*: slot timing

Time information:

- pulse (frame sync seq.) 
- time-stamp 

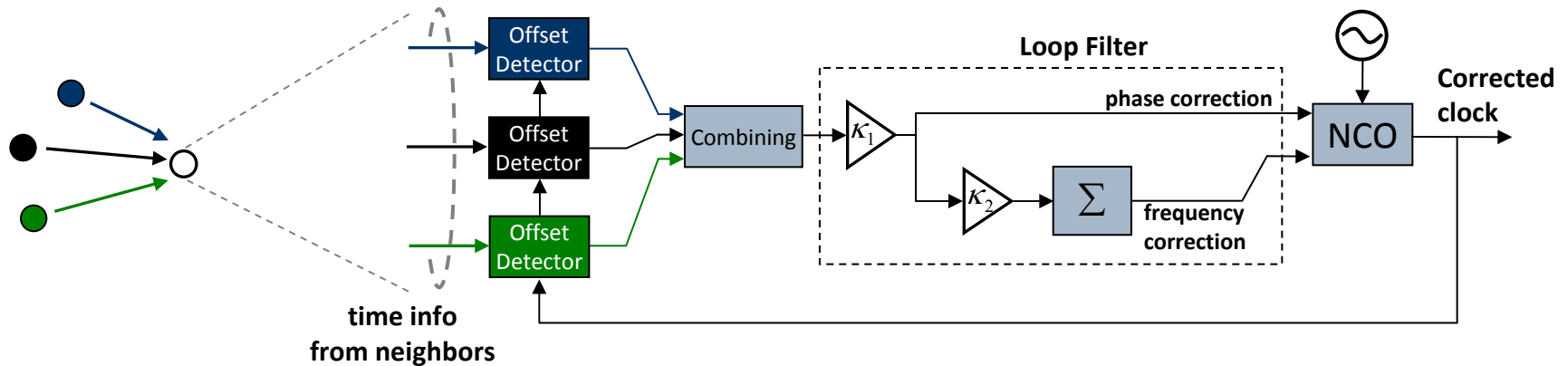
→ *access protocols for signaling slots*

NTP/PTP, others: handshakes 

our case: broadcast 

→ *no timing handshakes*

Each node employs time info to control the local clock via a PLL:



Analysis of *distributed* PLL:

- time sync *acquisition* (stability and conv. speed)
- steady-state accuracy:
 - *stable* clocks : frequency is constant bw updates
 - *unstable* clocks : frequency changes bw updates

Impact of topology

- MC
- MS

Choice of loop parameters:

- loop gain κ_1
- damping $\zeta(\kappa_1, \kappa_2)$

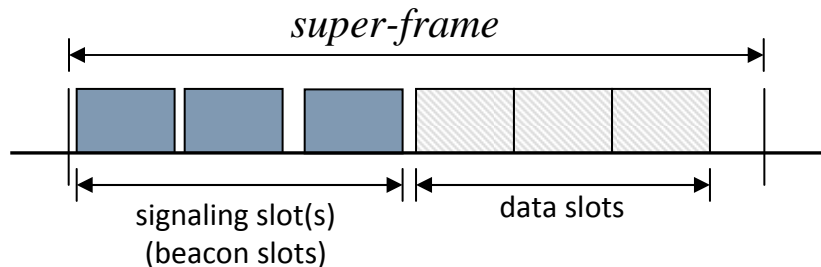


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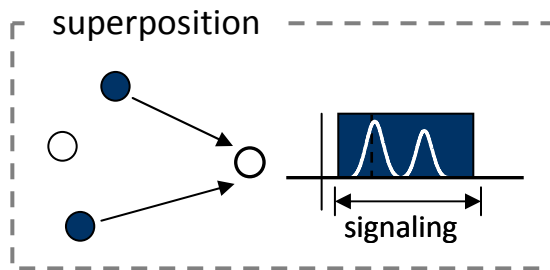
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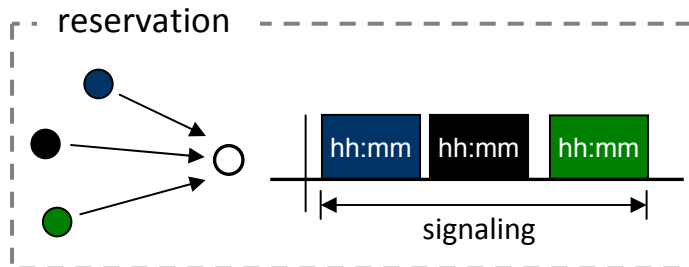
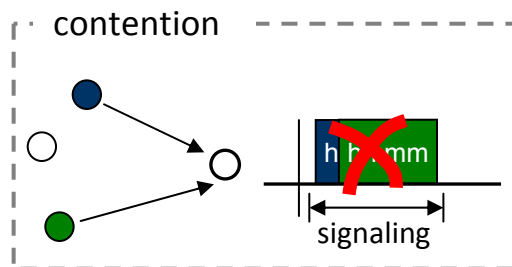


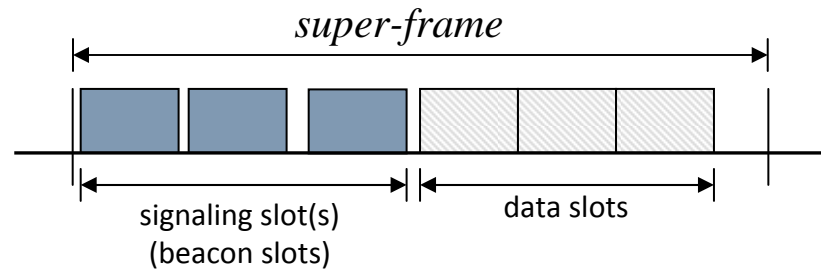
Time information:

- pulse (frame sync word)
→ *superposition* of pulses

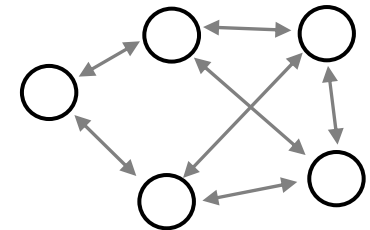


- time-stamp
→ *contention* or *reservation*-based transmission



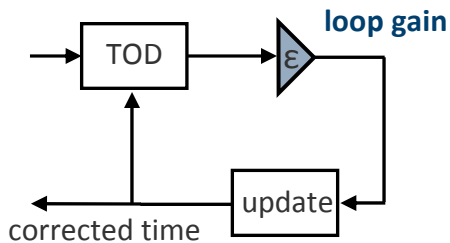


- acquisition trivial for MS \rightarrow analysis focused on *MC networks*
- *superposition* and *contention*:
 - almost sure convergence condition : convergence *in the mean*
- *reservation* :
 - overhead of signaling slots

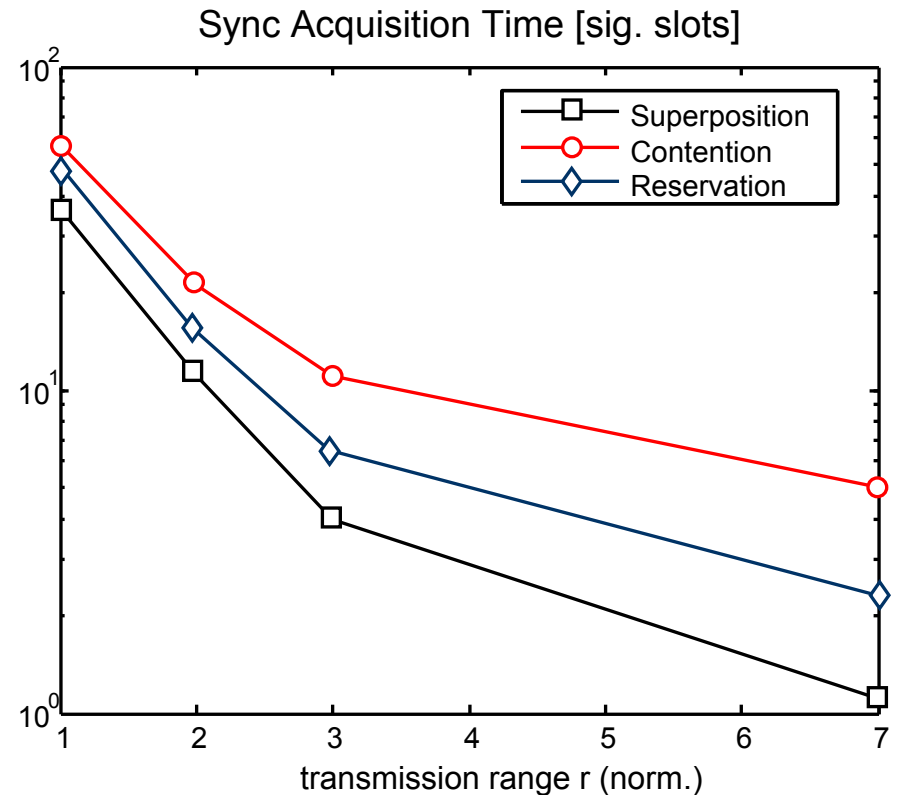
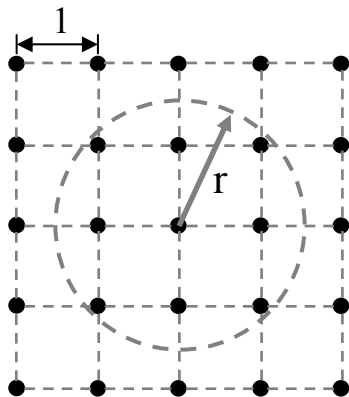




- Hp: clocks are frequency synchronous
 - Type 1 PLL for time (phase) sync



- $0 < \epsilon < 1$ ensures stability
- numerical optimization of loop gain ϵ for a given square lattice topology:

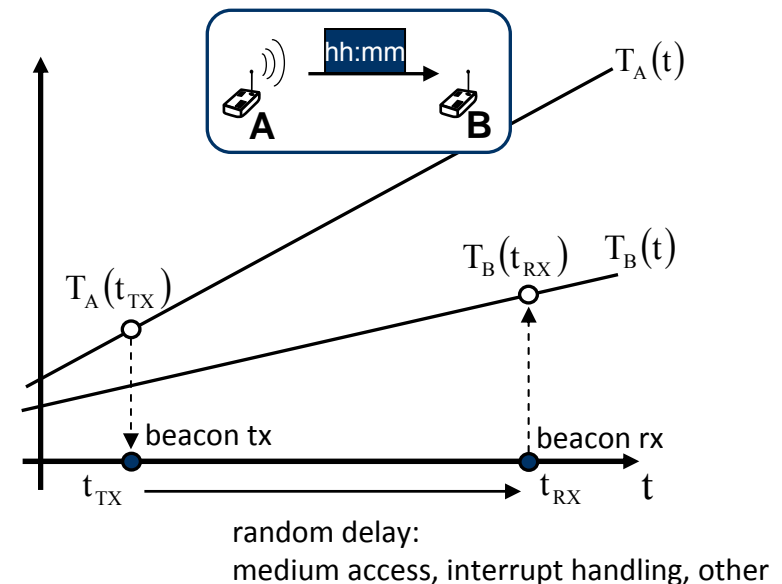
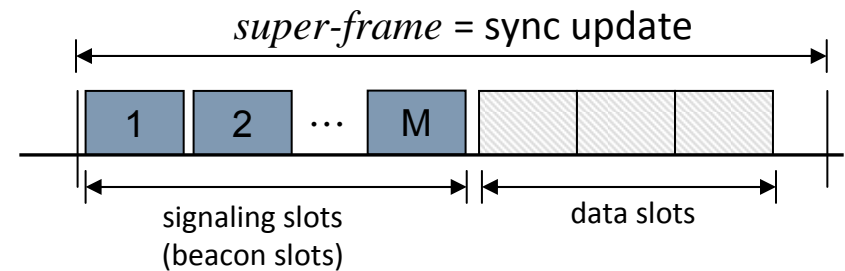




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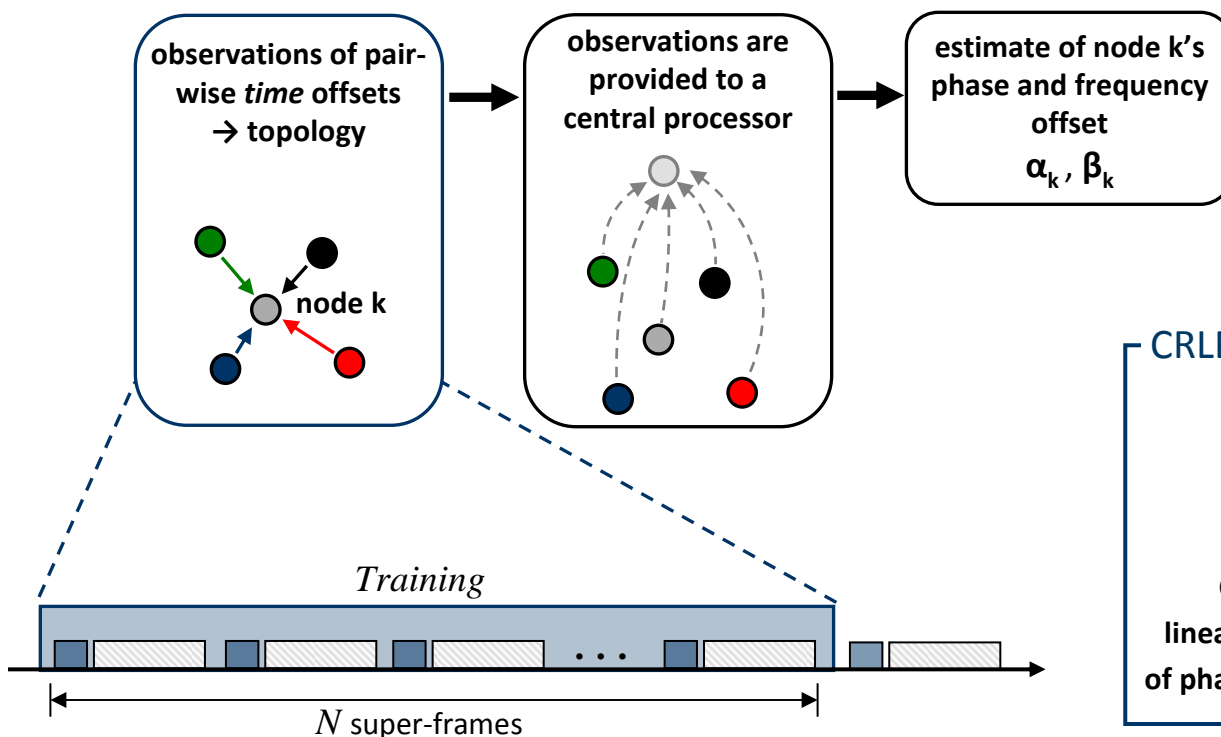
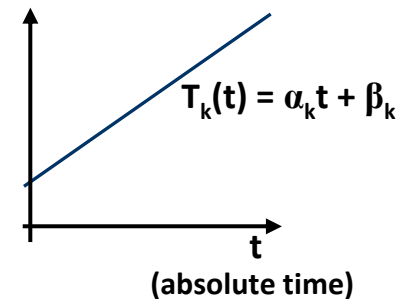


- TDMA MAC protocol
 - reservation-based signaling
- Hp: clk frequency is *stable*
 - linear clock model
- sync accuracy depends on *pair-wise offset* estimation errors.
 - delivery delays
 - clock precision (quantization)
- network sync posed as a (distributed) linear regression problem
 - distributed type 2 PLL
 - ➔ distributed linear regression (DLR)
 - ➔ *Cramér–Rao lower bound*





- CRLB: lower bound to clock parameter estimation error
 - linear clock model : estimate phase and frequency
 - time offset observations from signaling slots of subsequent super-frames
 - *centralized block-estimation* model:



CRLB for a general topology

$$\xi_{p,f}^2 \geq \rho_{p,f} \left[\frac{1}{K} \sum_{i=1}^{K_u} \frac{1}{\mu_i} \right]$$

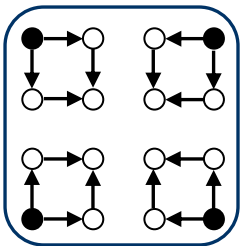
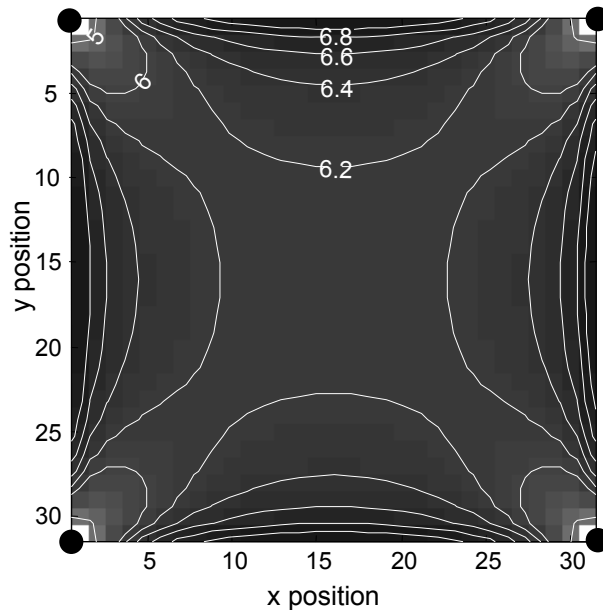
CRLB for linear regression of phase/frequency

sync network architecture

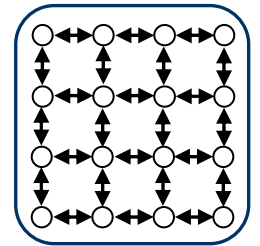
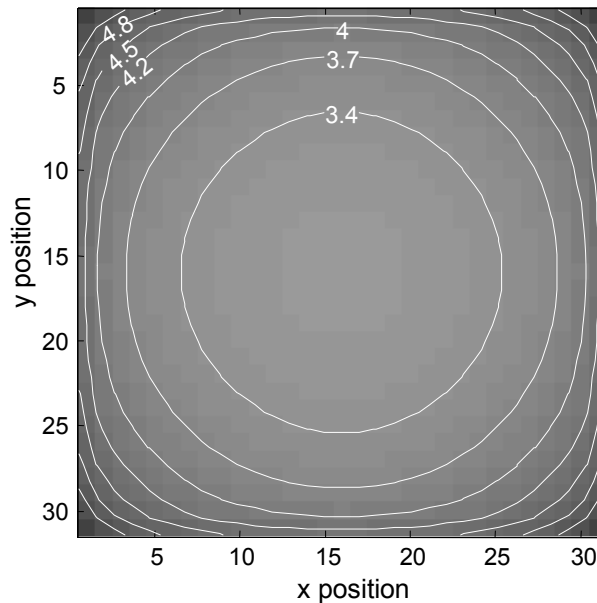


- Cramér–Rao lower bound for general sync architectures (MS, MC, hybrid)
 - MC: error distributed almost uniformly
 - MS: error distributed inhomogeneously - accuracy degrades rapidly moving away from masters
- CRLB for 2D 30x30 square lattice deployment (in μs)
(Gaussian offset measurement error with $10\mu\text{s}$ std dev, $N=10$)

MS architecture



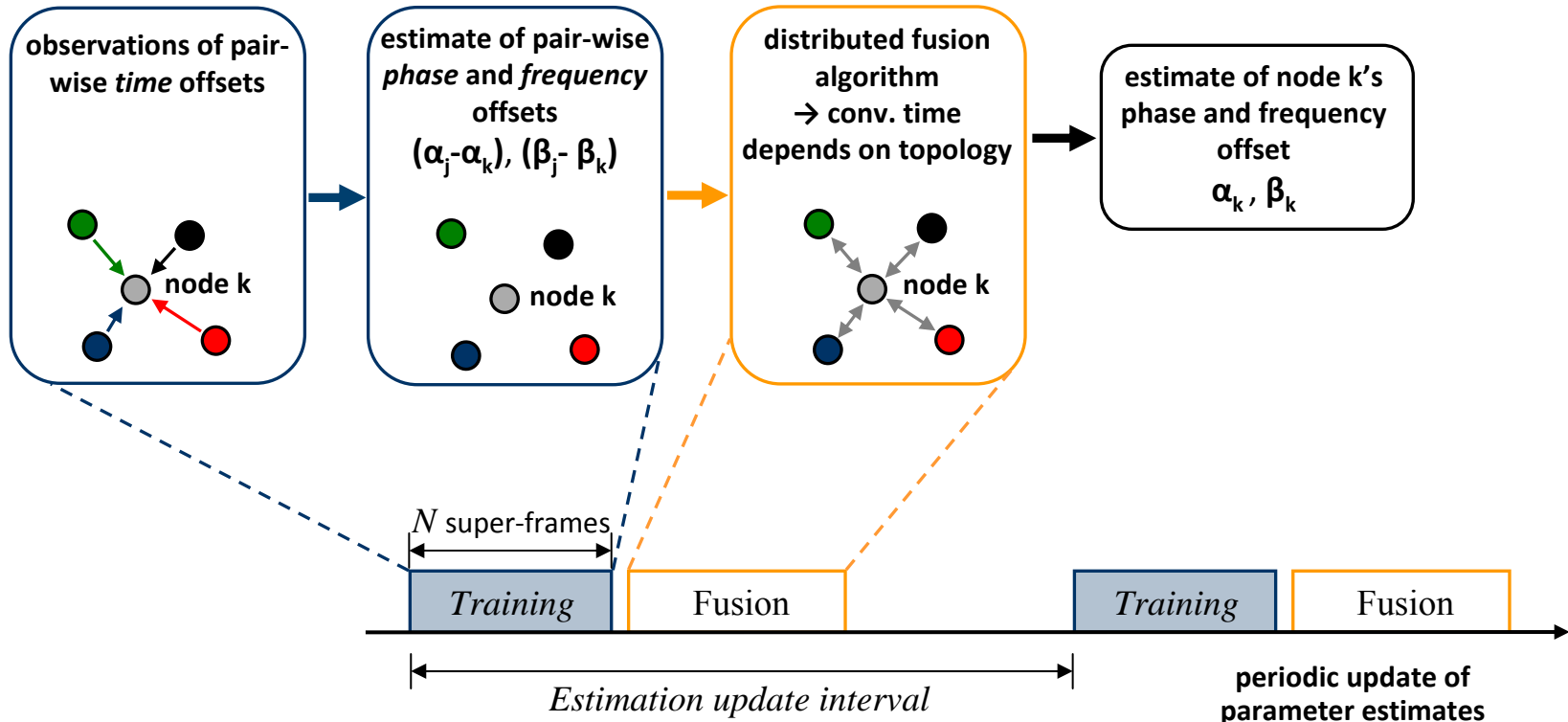
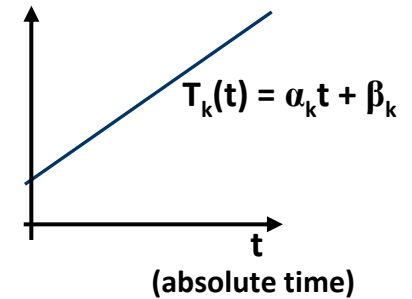
MC architecture





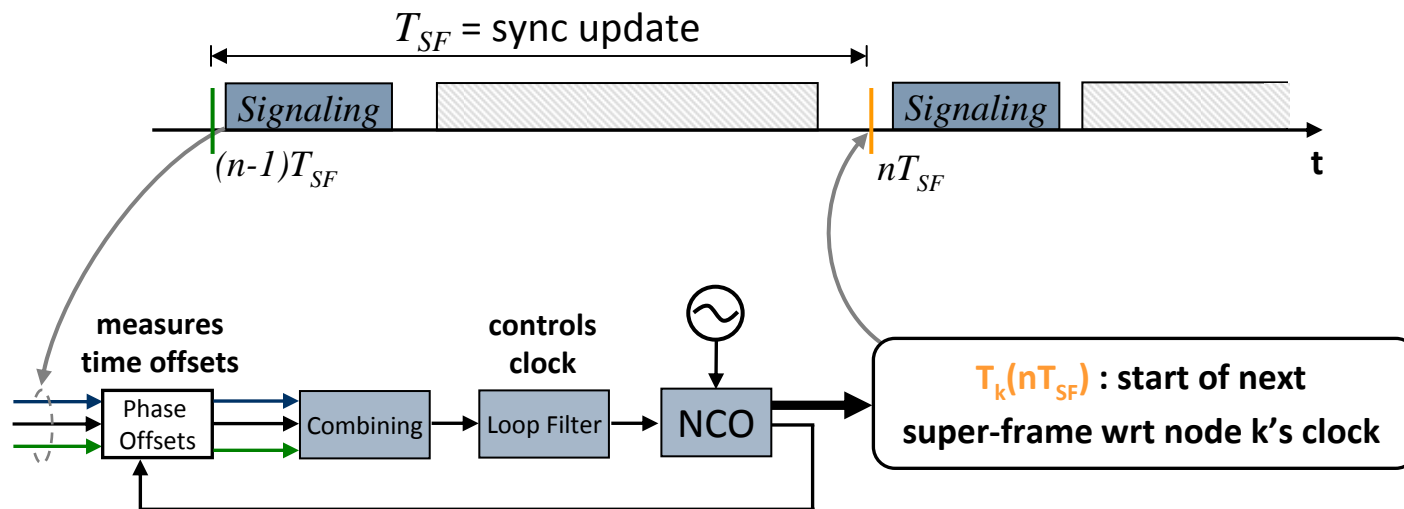
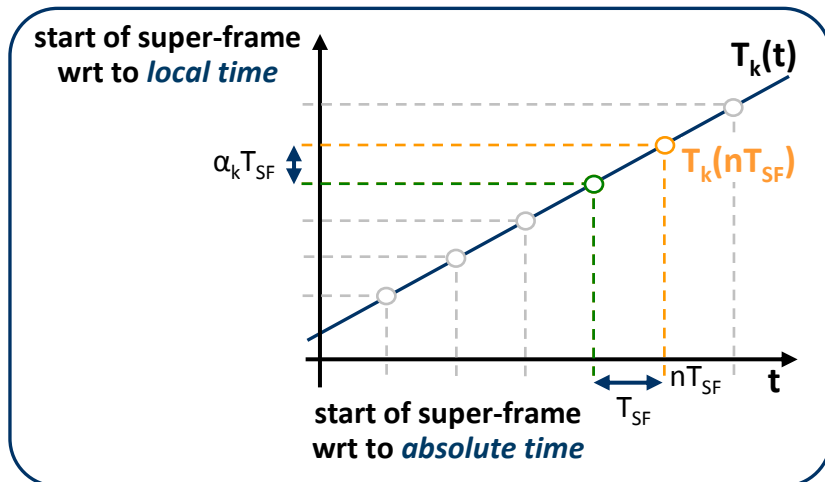
Distributed Linear Regression

- Design of *Distributed linear regression* (DLR) algorithm
 - linear clock model : estimate phase and frequency
 - time translation : $\mathbf{t} = (\mathbf{T}_k(\mathbf{t}) - \beta_k) / \alpha_k$
 - signaling slots employed for training and *distributed fusion*





- PLL clock control
 - linear clock model \rightarrow linear clock control
 - PI (type 2) controller: phase and frequency control
 - provides a prediction of the start time of next super-frame *wrt local clock*





- DLR: closed-form sync accuracy for general networks
- PLL: closed-form sync accuracy for regular MC networks

- *Effective* samples for PLL algorithms [Mengali94] →

$$N_{eff} = \frac{2}{\frac{\kappa_1}{2} \left(1 + \frac{\kappa_2}{\kappa_1} \right)}$$

- *Regular topology: ring network*

- CRB accuracy limit

$$\xi_{CRB}^2 \approx \frac{2\sigma_w^2}{N_{eff}} \frac{1}{\mu_2}$$

better connectivity improves accuracy

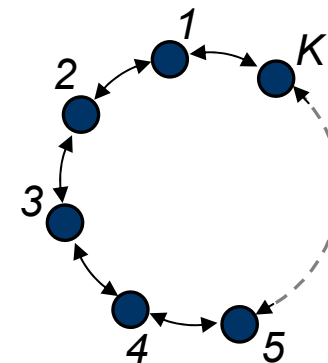
- DLR accuracy

$$\xi_{DLR}^2 \approx \frac{4d\sigma_w^2}{N_{eff}} \frac{1}{\mu_2^2}$$

- PLL accuracy

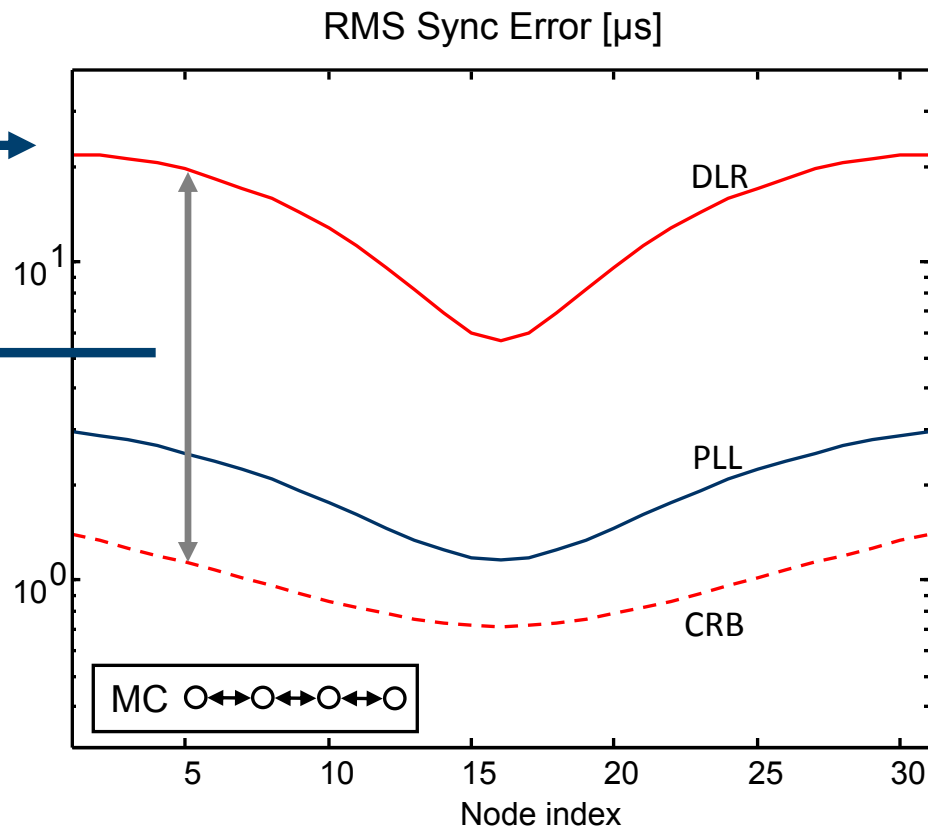
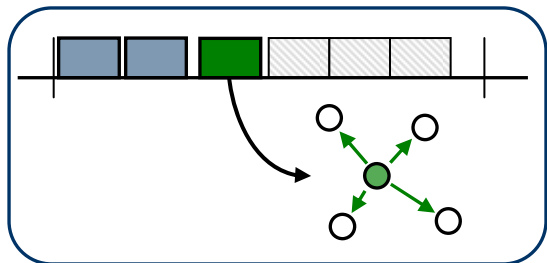
$$\xi_{PLL}^2 \approx \frac{4d\sigma_w^2}{N_{eff}} \frac{1}{\mu_2^2} \frac{1}{1 + 4\zeta^2}$$

improved noise filtering



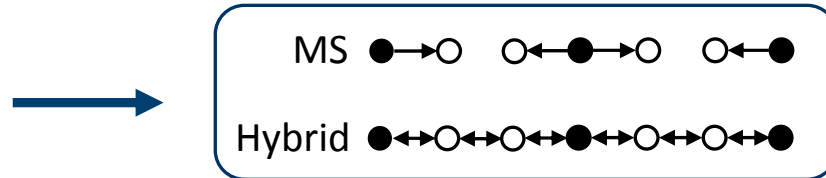


- Accuracy of practical algorithms over MC networks
- line network of 31 nodes, $N=1000$
- sub-optimality of both PLL and DLR wrt CRB
 - price to pay for *broadcast* signaling





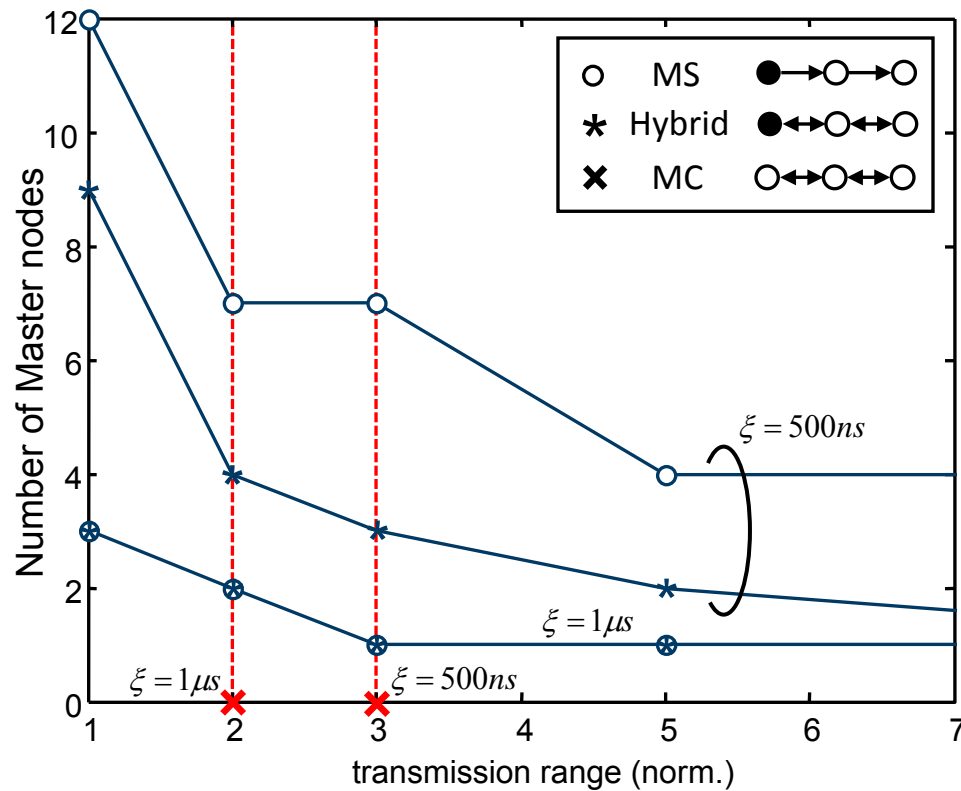
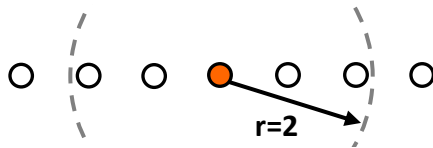
- Fix a desired time (phase) sync accuracy ξ
 - MC: accuracy improves *increasing transmission range*
 - MS/Hybrid: accuracy improves increasing transmission range or *master node density*



- MS/Hybrid: for a given transmission range, *how many master nodes do I need?*

- line network of 31 nodes, $N=1000$

- MC accuracy rapidly improves with transmission range





- ❑ Motivation

- ❑ Synchronization at the physical layer

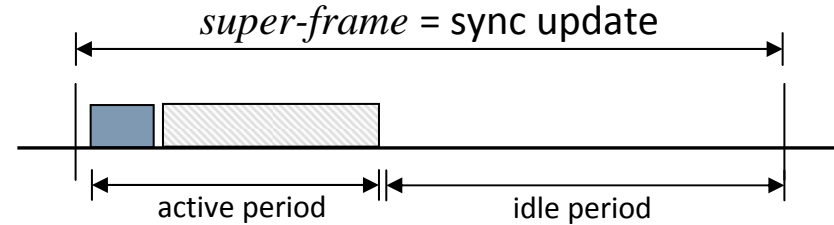
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- ❑ Conclusions



Sync Tracking with Low Duty-Cycles

- TDMA MAC protocol
 - reservation-based signaling
- low duty cycle → infrequent sync updates
 - clock is *unstable*: temp. changes

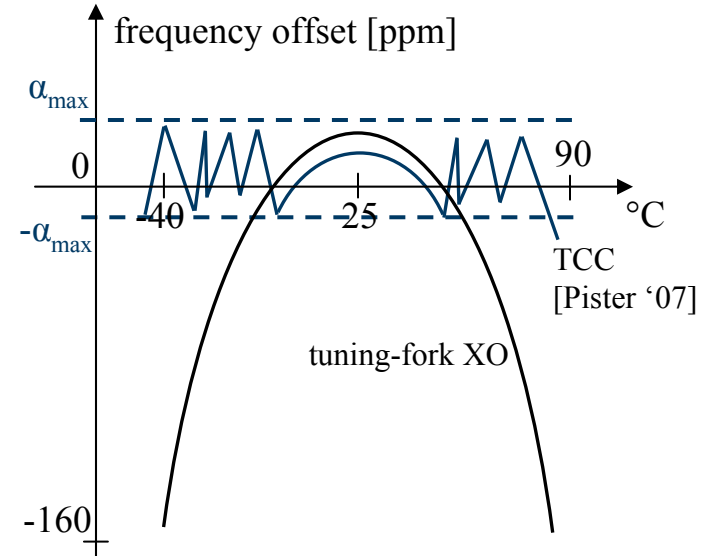


- *current solution*: static temp. compensation (Temp. Compensated Clock - TCC)
- achievable accuracy (lower bound for MS)



$$\xi = 2\alpha_{\max} T_{SF} + \delta$$

residual frequ. offset
phase offset estimation accuracy



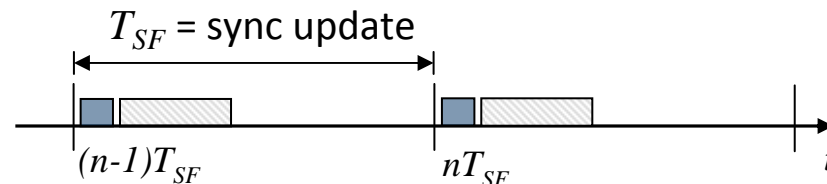


- Hp: clock frequency is the sum of two indep. random processes

$$\alpha(nT_{SF}) = \bar{\alpha} + \underbrace{v(nT_{SF})}_{\text{random walk (RWFM)}} + \underbrace{w(nT_{SF})}_{\text{white noise (WFM)}}$$

random walk (RWFM) white noise (WFM)

- WFM: noise within the oscillator
- RWFM: temperature changes, mechanical shocks and vibrations

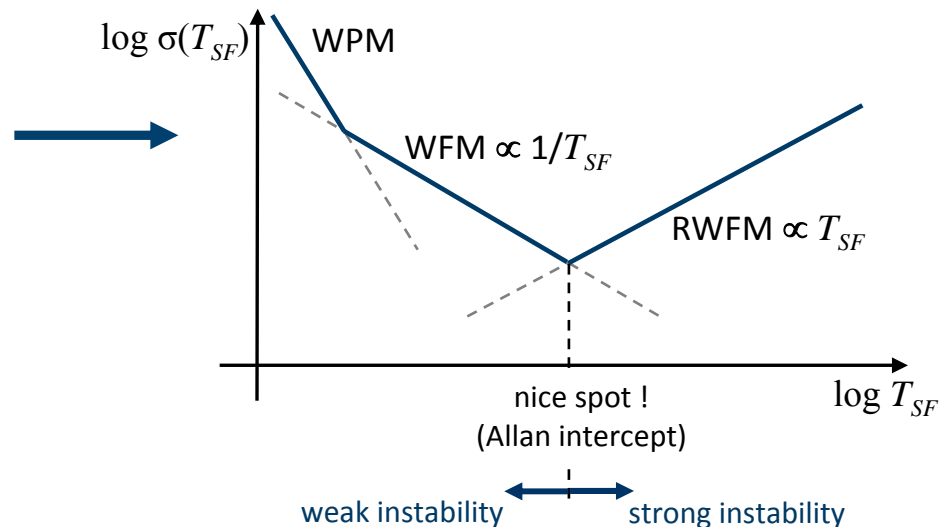


- Allan Variance: a measure of frequency stability

$$\sigma^2(T_{SF}) = E \left[\left| \alpha(nT_{SF}) - \alpha((n-1)T_{SF}) \right|^2 \right]$$

- *proposed solution: frequency tracking via:*

- Type 2 PLL
- Type 1 PLL+FLL (P/FLL)

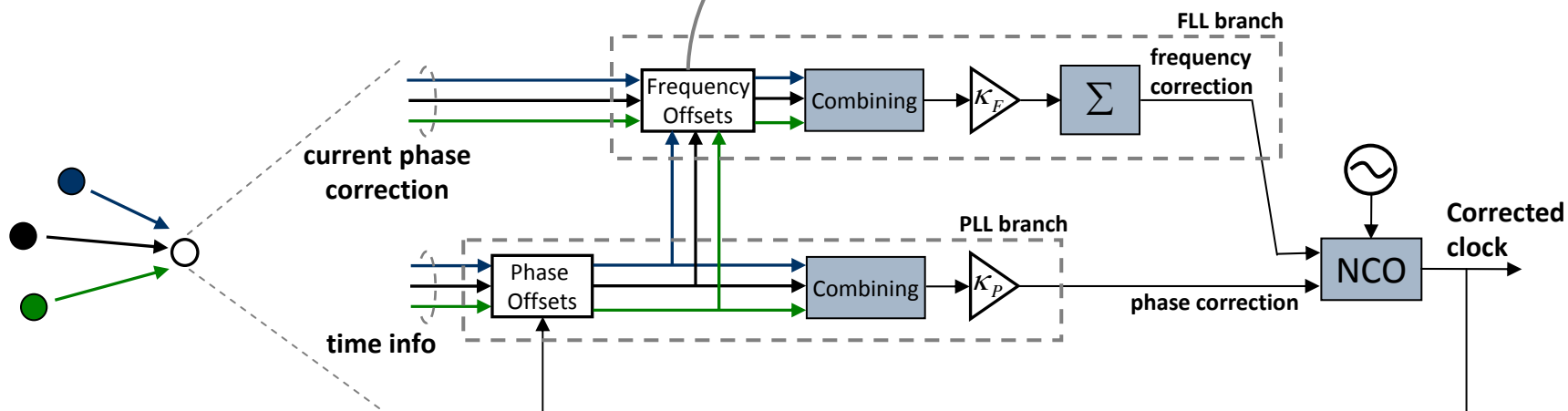
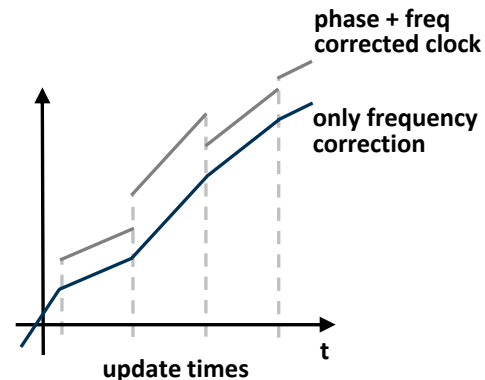




Type 1 PLL + FLL

Simpler design at the price of *increased overhead*

Frequency Offset Detector is sensitive only to frequency corrections



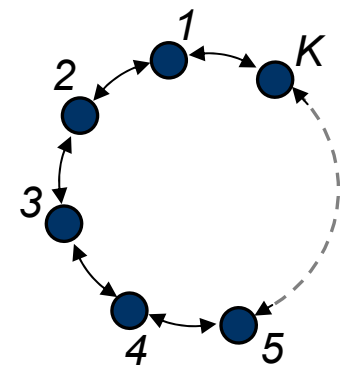


- Closed-form tracking accuracy in *regular* MC networks

$$\text{P/FLL} \quad \xi^2 \simeq \frac{1}{K} \sum_{i=2}^K \frac{1}{2\mu_i} \left[\left(\rho + \frac{\gamma}{\rho} \right) \frac{\sigma_w^2}{d} + \frac{\sigma_v^2}{\rho} + \frac{\sigma_\eta^2}{\mu_i^2 \gamma \rho} \right]$$

$$\text{Type 2 PLL} \quad \xi^2 \simeq \frac{1}{K} \sum_{i=2}^K \frac{1}{2\mu_i} \left[\left(\kappa_1 + \frac{\kappa_2}{\mu_i} \right) \frac{\sigma_w^2}{d} + \frac{\sigma_v^2}{\kappa_1} + \frac{\sigma_\eta^2}{\kappa_2 \kappa_1 \mu_i} \right]$$

network connectivity channel noise (time offset estimation error) tracking error (WFM + RWFM)



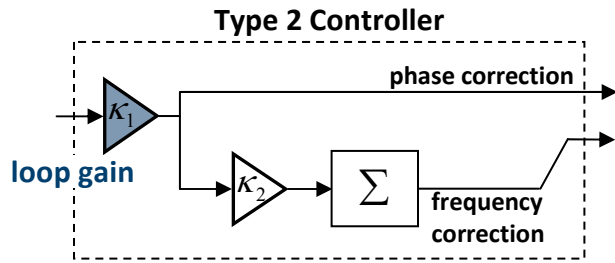
- better connectivity improves sync accuracy
- trade-off between channel noise reduction and frequency tracking
- integral gain κ_2 proportional to loop gain κ_1 :
 - small κ_1 improves channel noise rejection
 - large κ_1 improves tracking accuracy of unstable clocks

—————> previous part

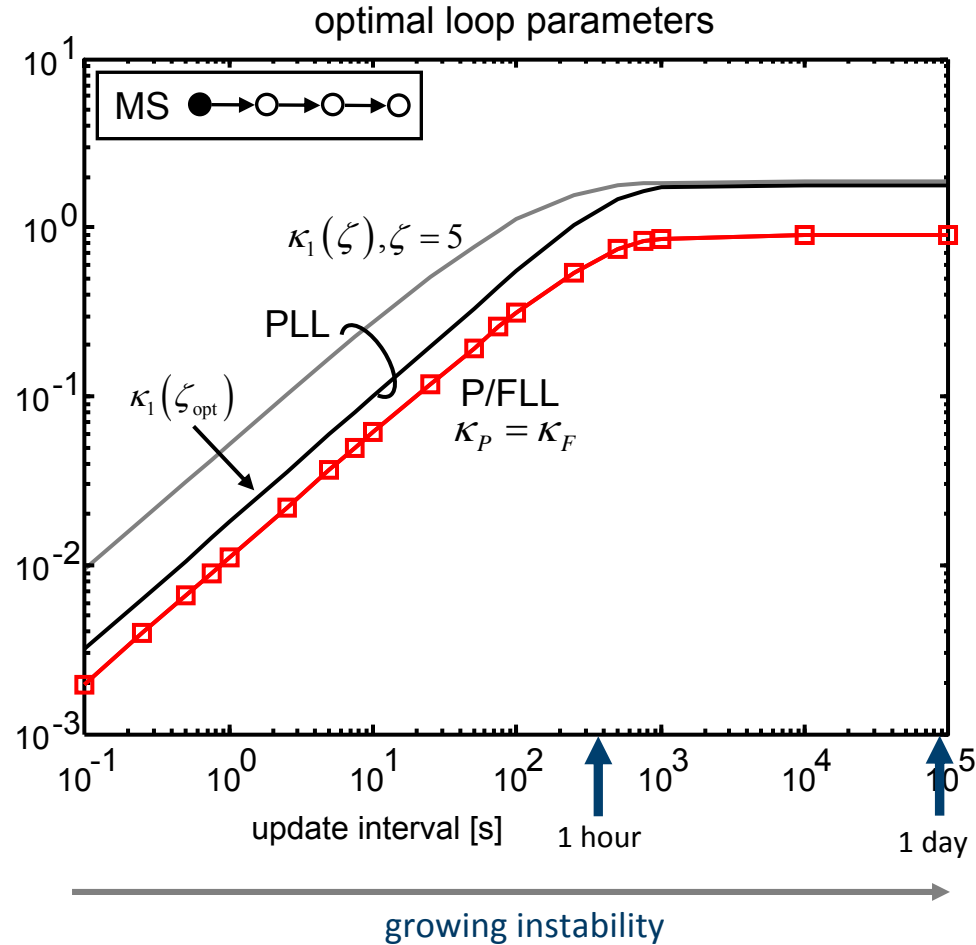


- Numerical optimization of loop parameters

- P/FLL: opt. PLL gain κ_p + opt. FLL gain κ_f
 - PLL: - optimize jointly *l.gain*/damping
- fix damping and optimize *l.gain*



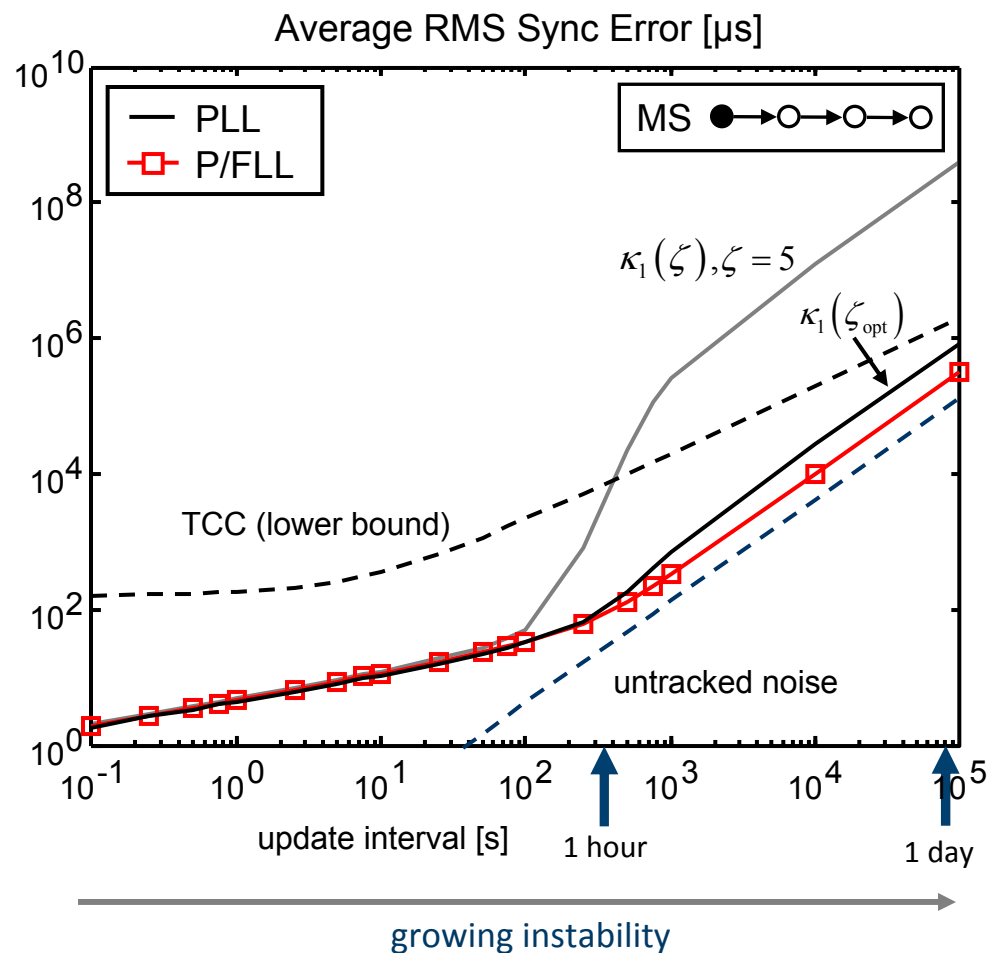
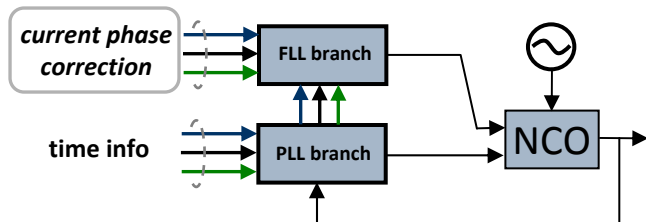
- MS line network of 30 nodes
- 1°C temp change within 1 hour
- gain increases proportionally with clock instability





- Average synchronization error for a line MS network of 30 nodes
- 1°C temp change per 1 hour
- adaptive clock control outperforms TCC
- adaptation complexity
 - for optimal performance, PLL requires to *jointly* adapt damping and loop gain
 - optimization of PLL and FLL branch is *independent* in a P/FLL

Simpler design at the price of increased overhead





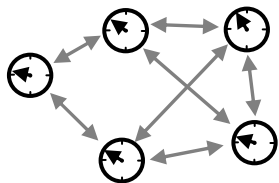
- Motivation
- Synchronization at the physical layer
- Synchronization at the MAC layer
- Conclusions



- Advocate network sync via PLL/FLL techniques
 - can be applied at PHY/MAC/APP layer at the protocol stack
 - ➔ robust wrt RF *signal superposition* and *packet collisions*
 - general-purpose tool for *both MS/MC sync architectures*
 - ➔ allow for improved *sync accuracy* and *tracking performance*
 - can be adapted to large update periods (*low duty-cycles*) ➔ WSN based on TDMA
- Best flat (MC) or hierarchical (MS) sync architecture ?

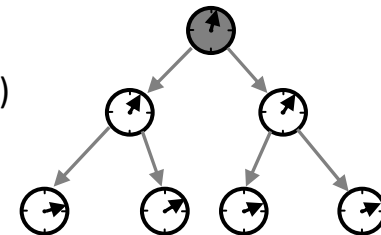
MC

- + fully decentralized
- + robust wrt node failures
- + smooth error distribution
- slow convergence



MS

- + natural arch. for hierarchical networks
- + fast convergence
- error accumulation away from master(s)
- fragile to node failures





This seminar: Design of distributed clock control algorithms

Future work:

- Design algorithms that dynamically adapt loop parameters to
 - topology (connectivity)
 - architecture (MS/MC)
 - duty cycles (energy efficient sync)
 - clock quality (frequency instability)
 - channel error statistics→ lessons learned from packet-based sync algorithms (NTP)
- Implementation of the designed algorithms
 - improvements to the efficiency of currently employed TDMA MAC protocols (e.g., IEEE 802.15.4e)
 - complexity/computational cost



RELATED PUBLICATIONS

- N. Varanese, U. Spagnolini and Y. Bar-Ness, “*Synchronization tracking with low duty cycles*”, in preparation.
- N. Varanese, U. Spagnolini and Y. Bar-Ness, “*On the accuracy of distributed synchronization algorithms for wireless networks*”, in preparation.
- N. Varanese, U. Spagnolini and Y. Bar-Ness, “*Distributed frequency-locked loops for wireless networks*”, submitted to IEEE Trans. on Communications (*second review round*).
- N. Varanese, Y. Bar-Ness and U. Spagnolini, “*On the synchronization rate of distributed medium access protocols*,” Proc. Conference on Information Sciences and Systems (CISS) 2010, Princeton, NJ USA, March 17-19, 2010.
- U. Spagnolini, N. Varanese, O. Simeone and Y. Bar-Ness, “*Distributed Digital Locked Loops for time/frequency locking in packet-based wireless communication*,” in Proc. IEEE PIMRC 2008, Cannes, France, Sept. 15-18, 2008 (invited paper).
- N. Varanese, O. Simeone, Y. Bar-Ness and U. Spagnolini, “*Distributed Frequency-Locked loops for wireless networks*,” in Proc. IEEE ISSSTA 2008, Bologna, Italy, Aug. 25-28, 2008.



Questions ?

